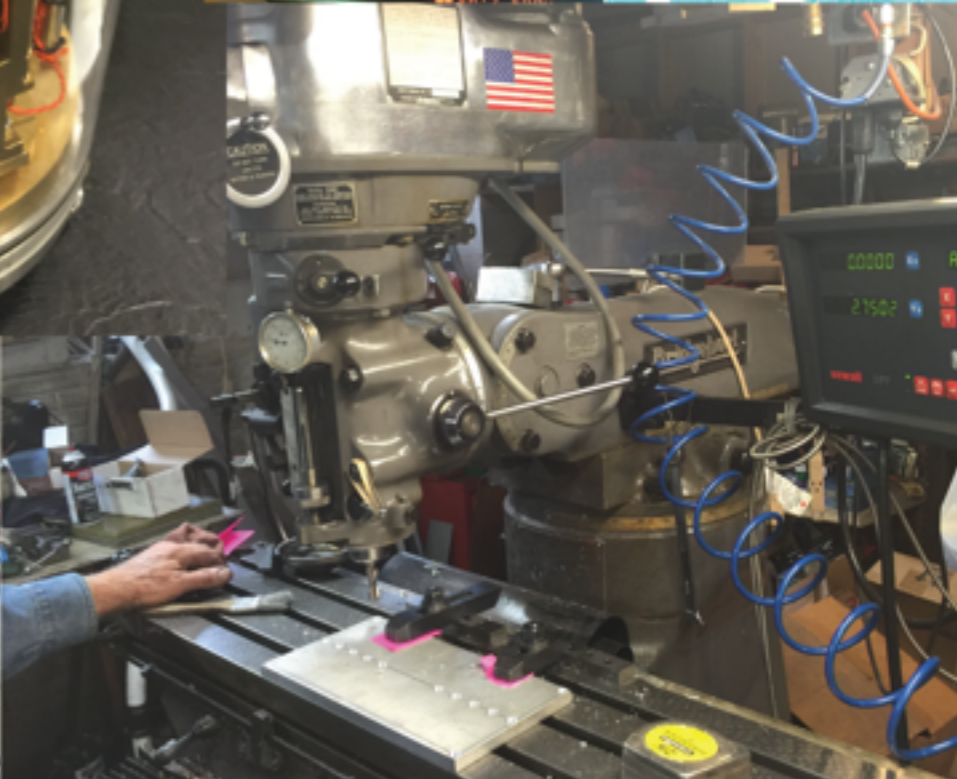
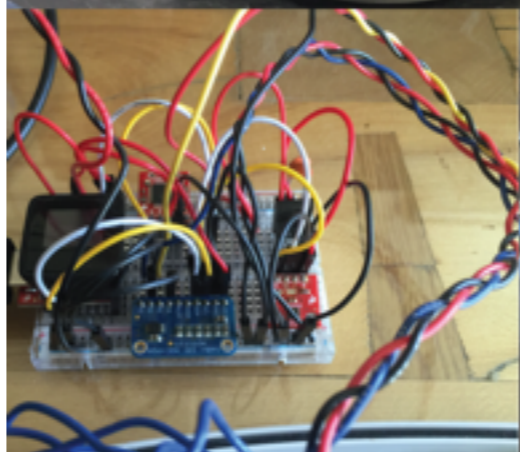
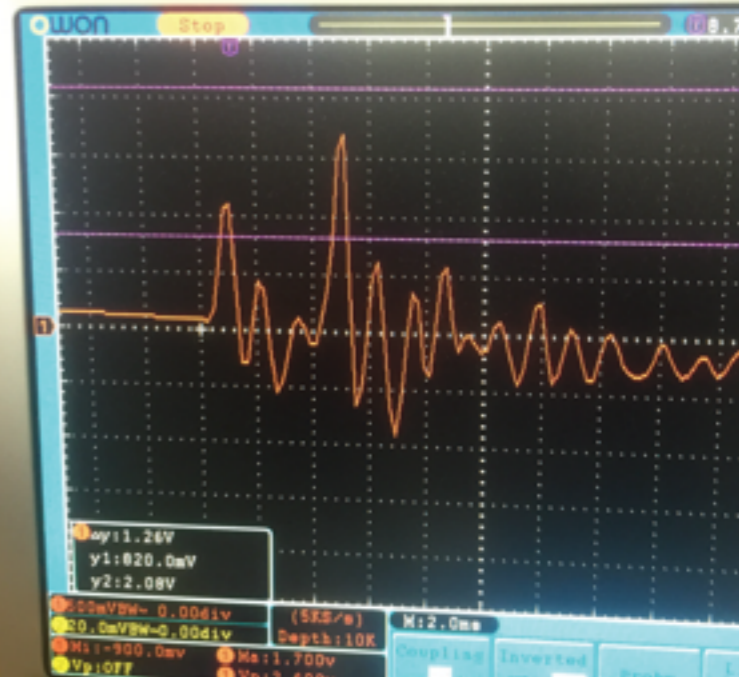
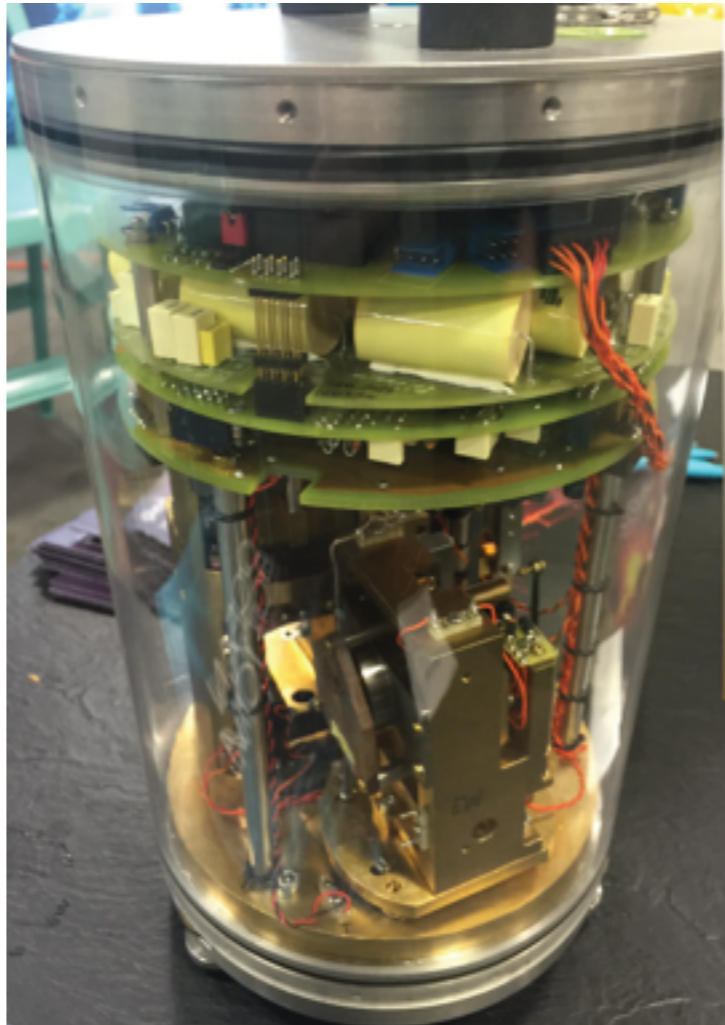


Transducers

J.R. Leeman and C. Marone

Techniques of Geoscientific
Experimentation

October 18, 2016



Transducers are devices that convert one form of energy to another - we commonly use them as real-world interfaces

Active

Passive

Actuator





Bidirectional

Transducer Selection

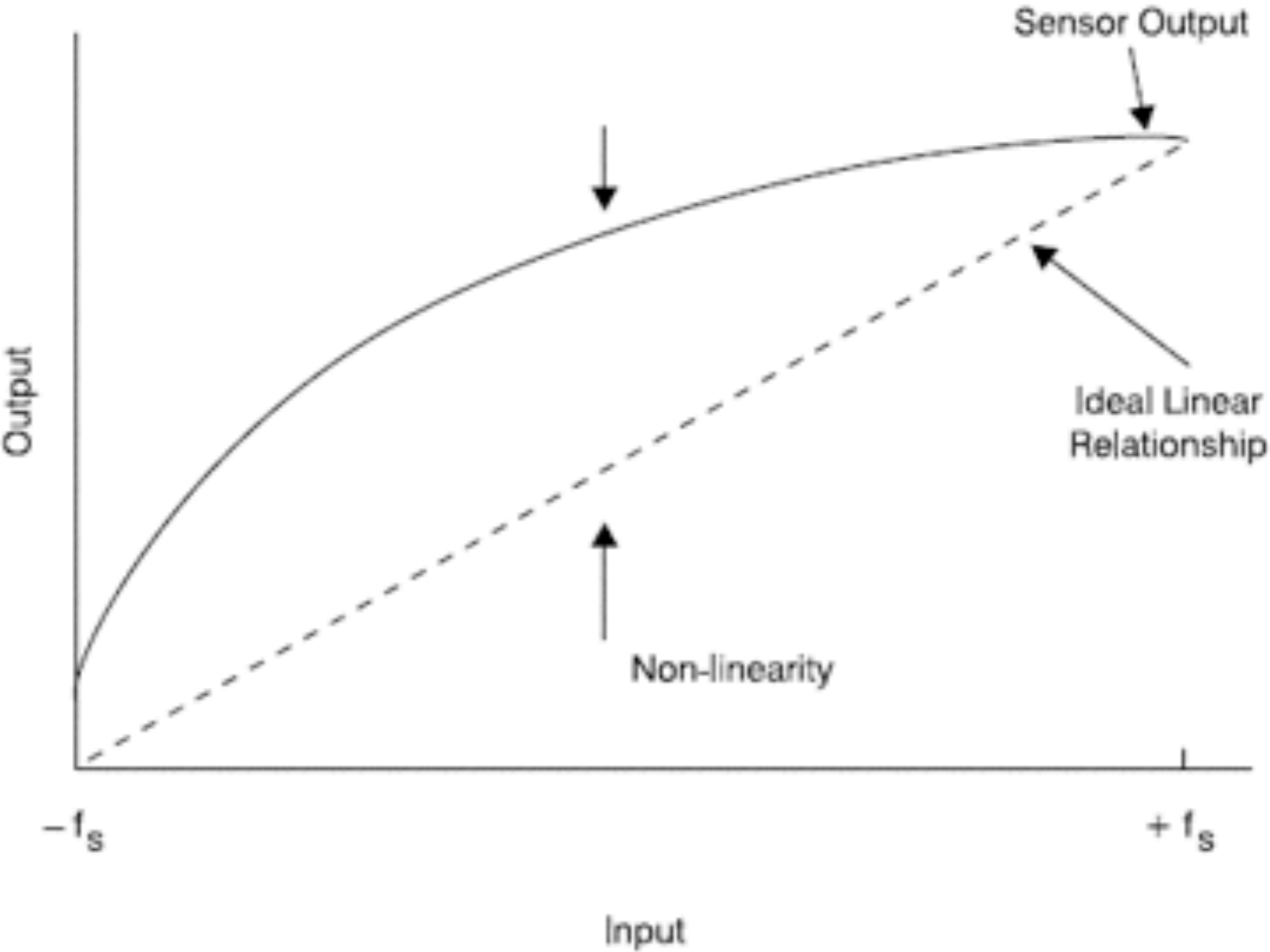
When selecting a transducer, you must have a well defined application and consider a number of variables

- **Range**
- **Linearity**
- **Sensitivity**
- **Response Time**
- **Stability**
- **Accuracy**
- **Durability**
- **Cost**
- **Signal Conditioning**

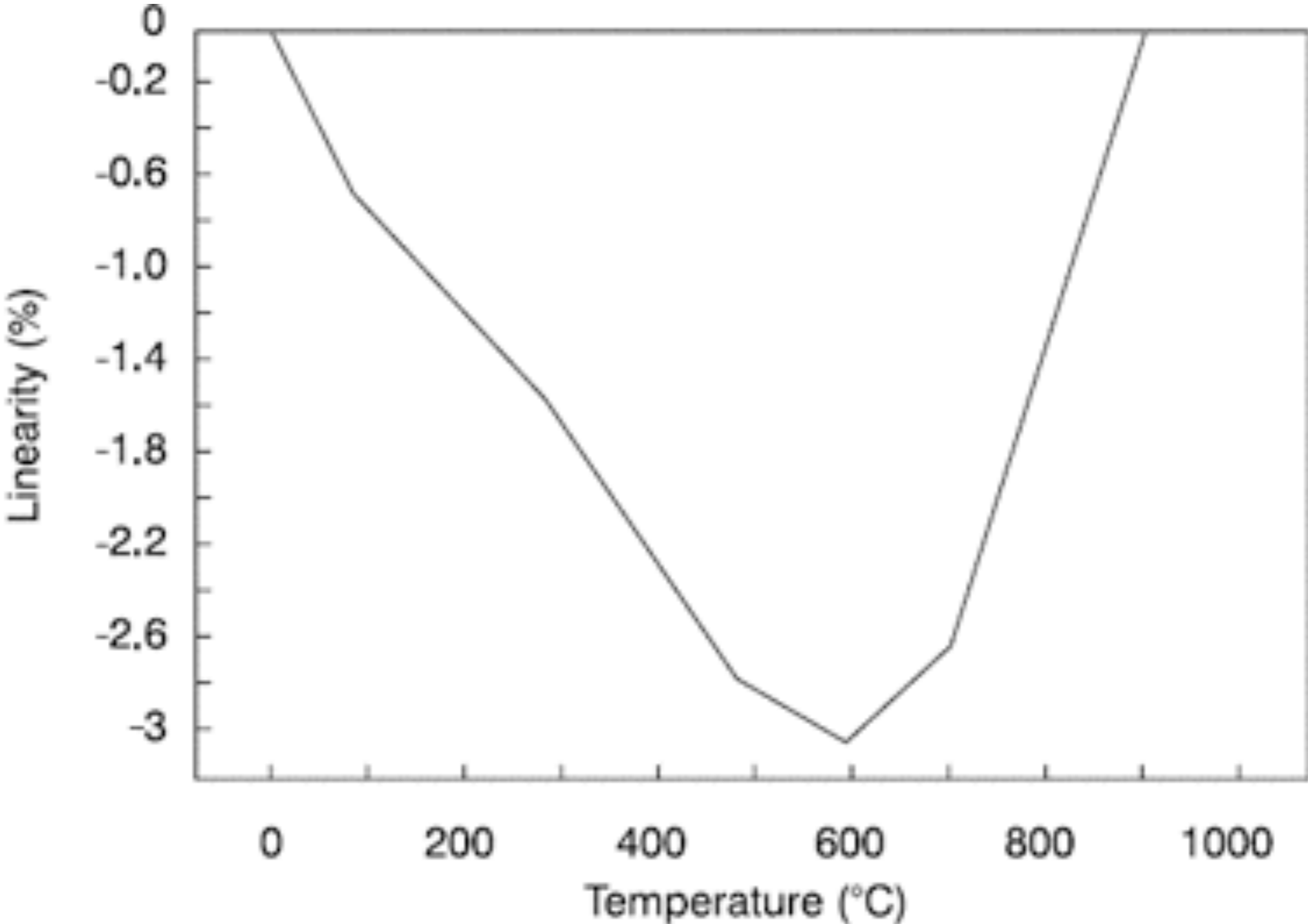
Range is the span of values over which the transducer is rated to perform at

	Elite Series Best Performance Modular Design		CPL230 Great Performance Compact Multi	CPL350 Great Performance Compact Single	CPA100 Analog Proximity Lower Cost
					
	CPL490	CPL190/290			
Ranges	10-200 μm	10 μm to 12.5 mm	10 μm to 12.5 mm	10 μm to 12.5 mm	50 μm to 12.5 mm
Typical Resolution* @ 15 kHz	0.0007% F.S.*	0.003% F.S.*	0.004% F.S.*	0.004% F.S.*	0.03% F.S.*
Typical Linearity*	0.2%	0.2%	0.5%	0.5%	Nonlinear
Max Bandwidth	50 kHz	15 kHz	15 kHz	15 kHz	15 kHz
Zero/Offset Adjust	Yes	Yes	No	No	Yes
Gain Adjust	No	No	No	No	Yes
Setpoint/Switch Output	No	No	No	No	Yes
Typical Thermal Drift*	0.02% F.S./ $^{\circ}\text{C}$	0.04% F.S./ $^{\circ}\text{C}$	0.04% F.S./ $^{\circ}\text{C}$	0.04% F.S./ $^{\circ}\text{C}$	Driver: 0.2% F.S./ $^{\circ}\text{C}$ Probe: 0.05% F.S./ $^{\circ}\text{C}$
LED Range Indicator	Yes	Yes	No	No	Yes
Cost	\$\$\$\$	\$\$\$	\$\$	\$\$	\$
Other Features	Optional Signal Processing and Meter Module Easy DAQ connection		Embeddable/OEM Design	Embeddable/OEM Design	Remote Zero and Gain Setpoint/Switch output

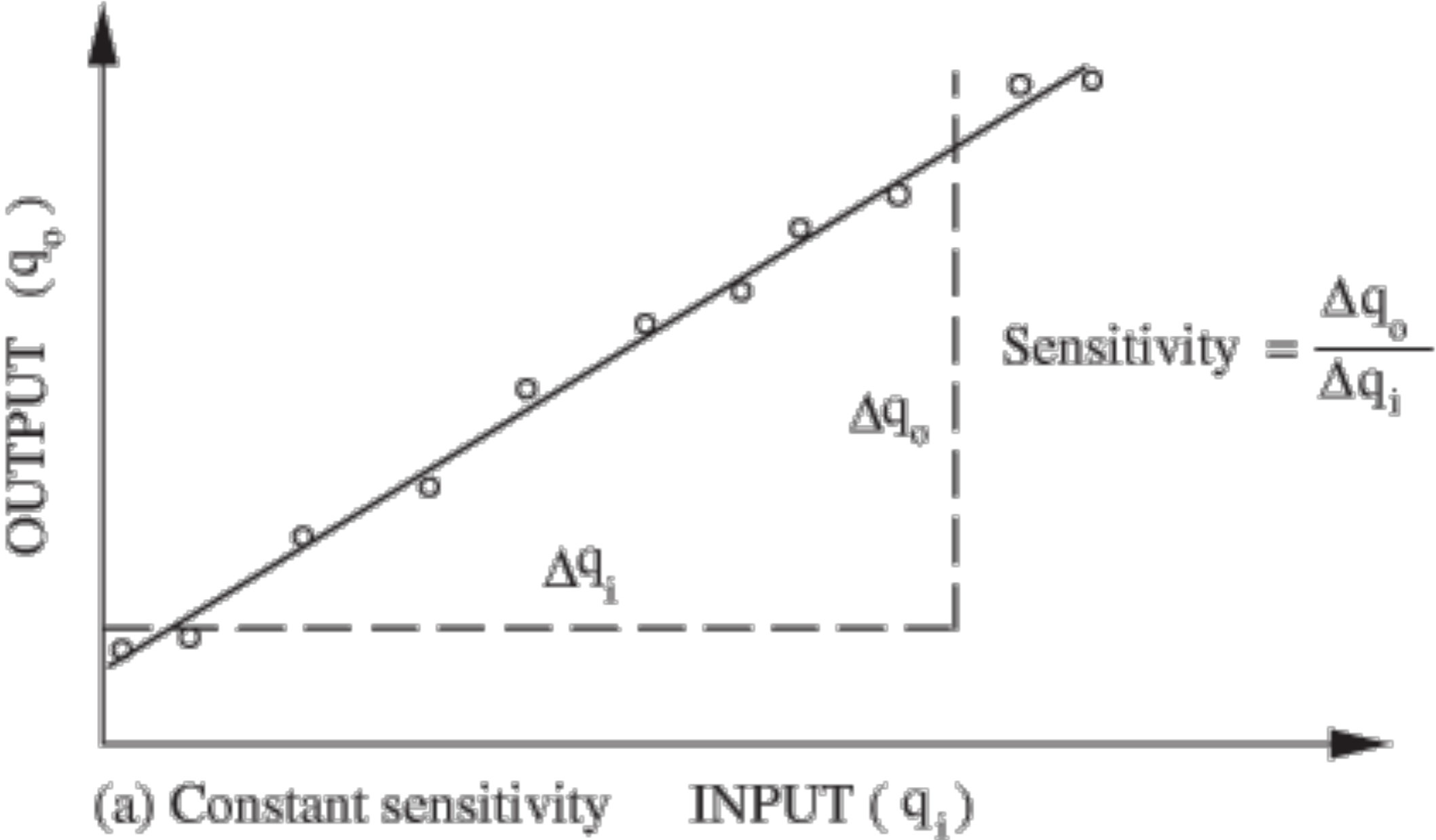
Linearity is how much the sensor diverges from an ideal linear sensor output



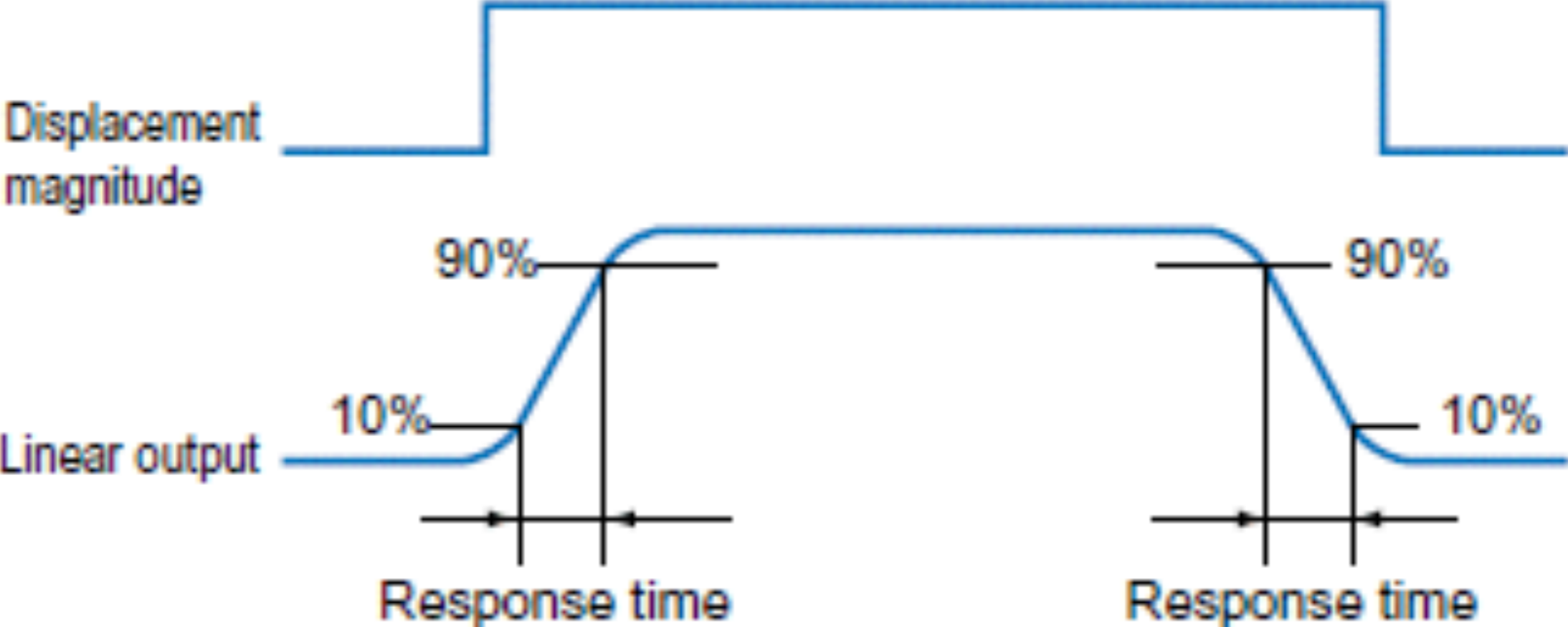
Linearity is how much the sensor diverges from an ideal linear sensor output



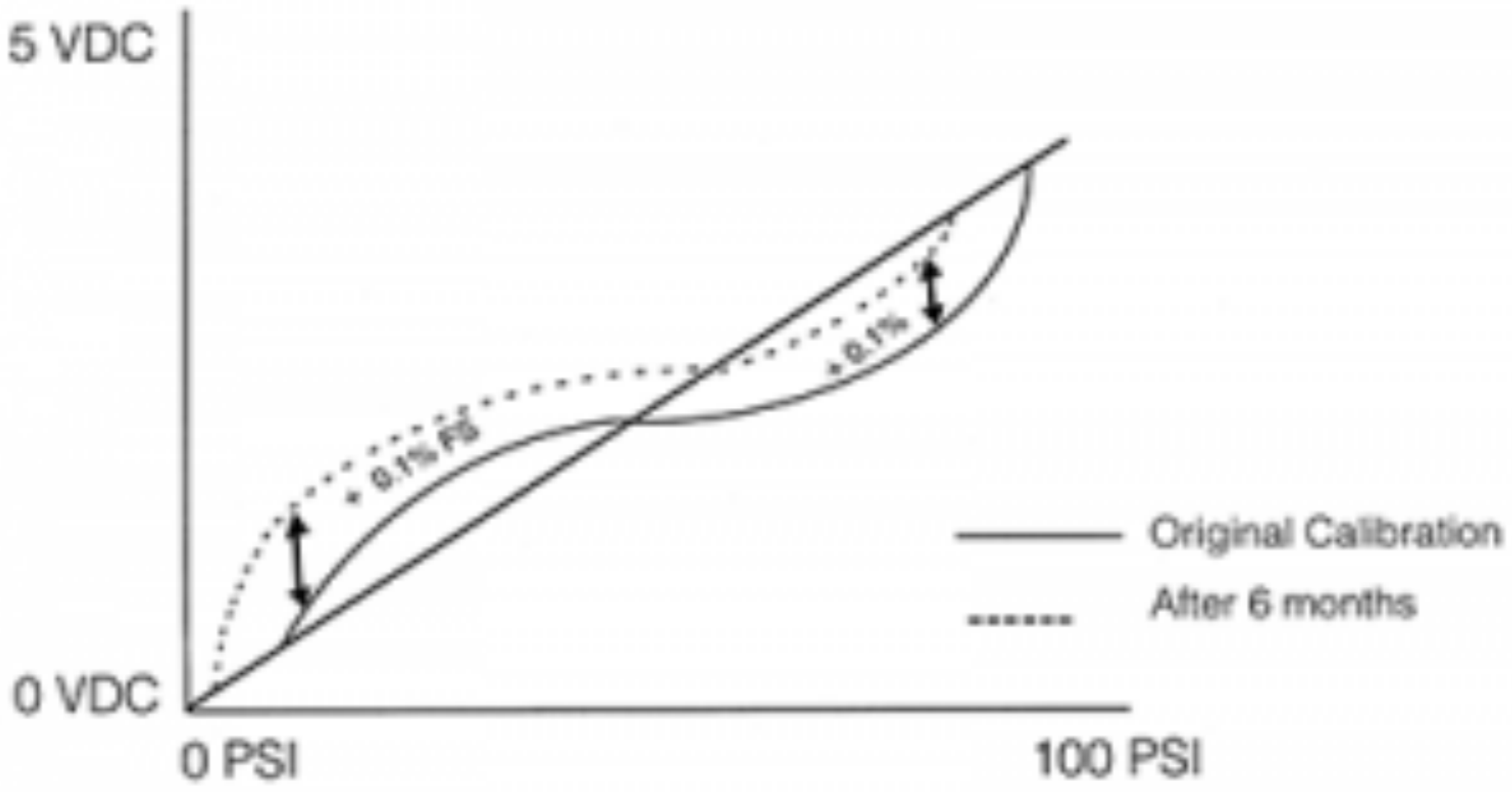
Sensitivity is the slope of the output - input curve



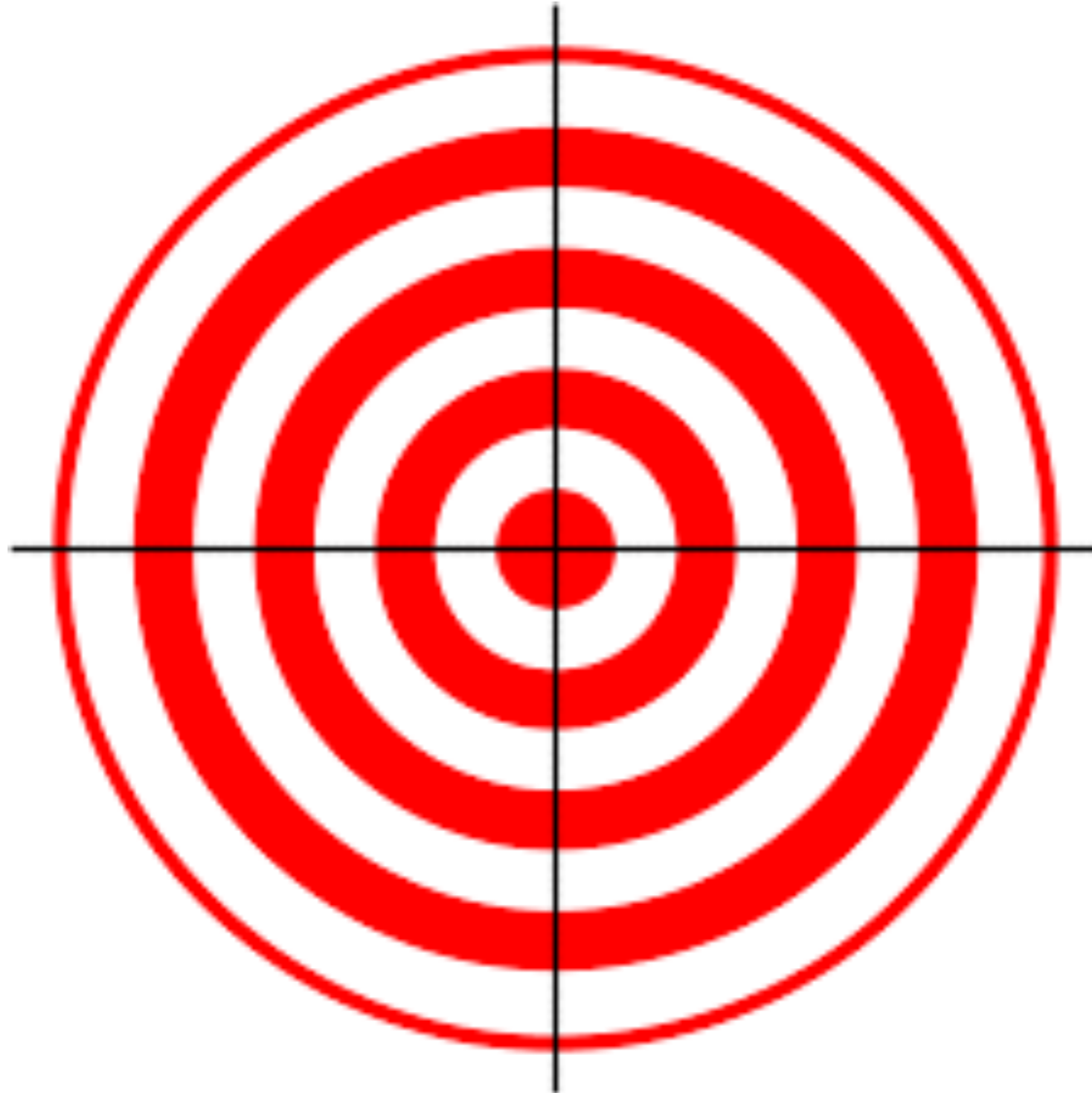
Response time is how long the transducer takes to register a change in the physical quantity



Stability is how constant the output of a transducer remains when the physical stimulus is static



Precision refers to the reproducibility of a given measurement



Accuracy is the maximum difference between the real and indicated values

Durability is how rugged the transducer is to the measurement environment it will be exposed to

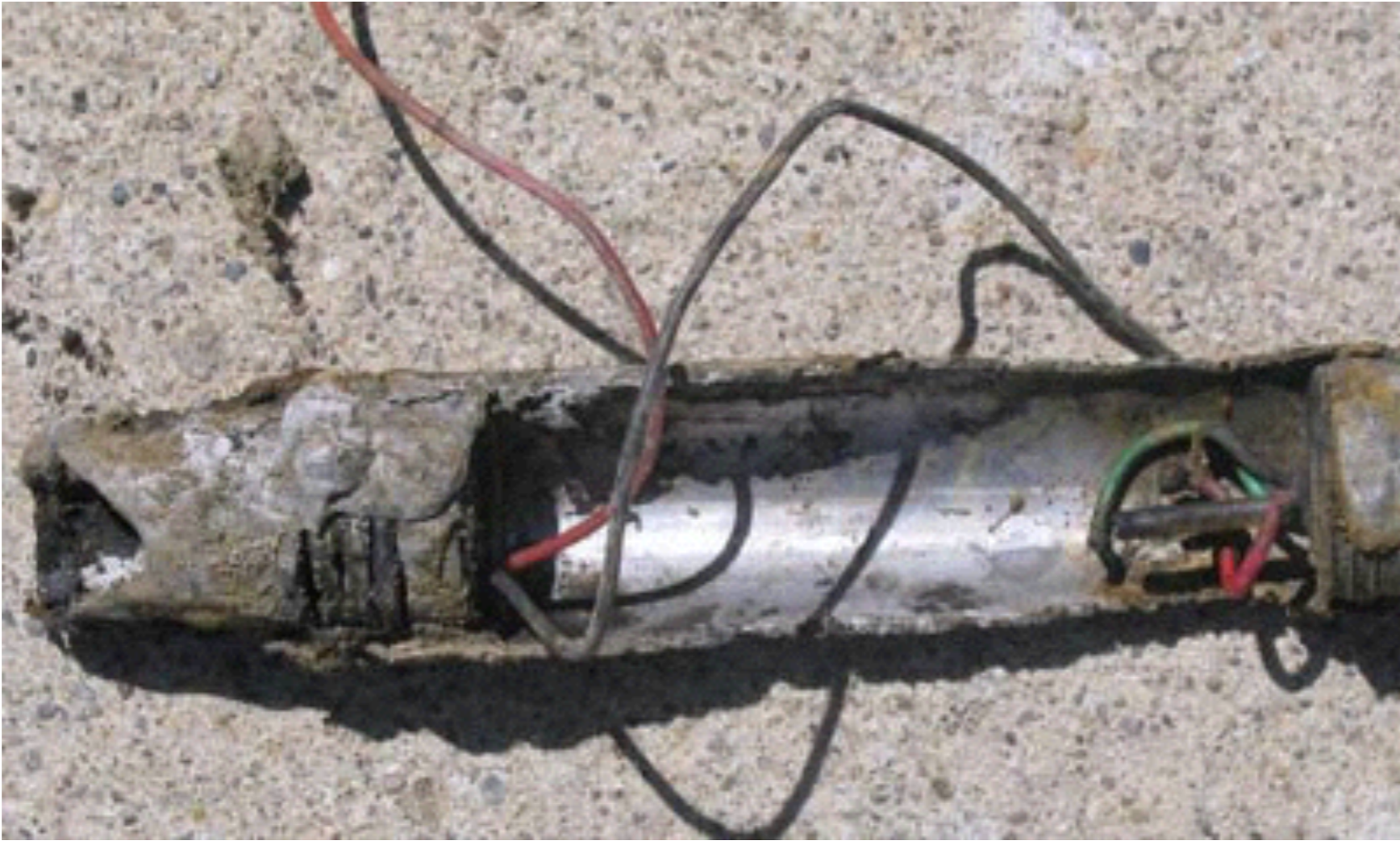


Image: APG Sensors

Signal conditioning requirements can greatly impact the ease of use and cost of a given transducer

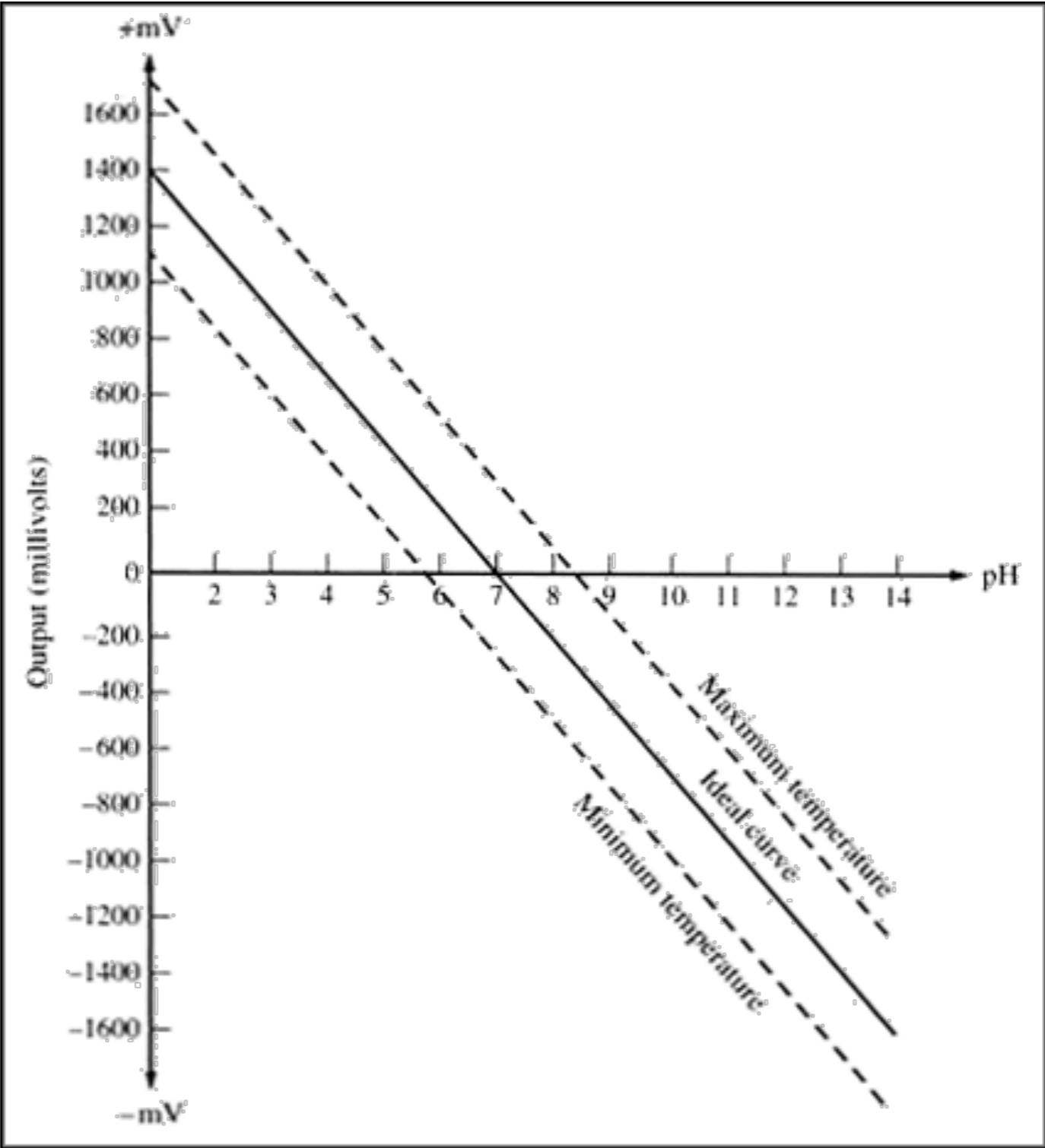
Modular Signal Conditioning Systems



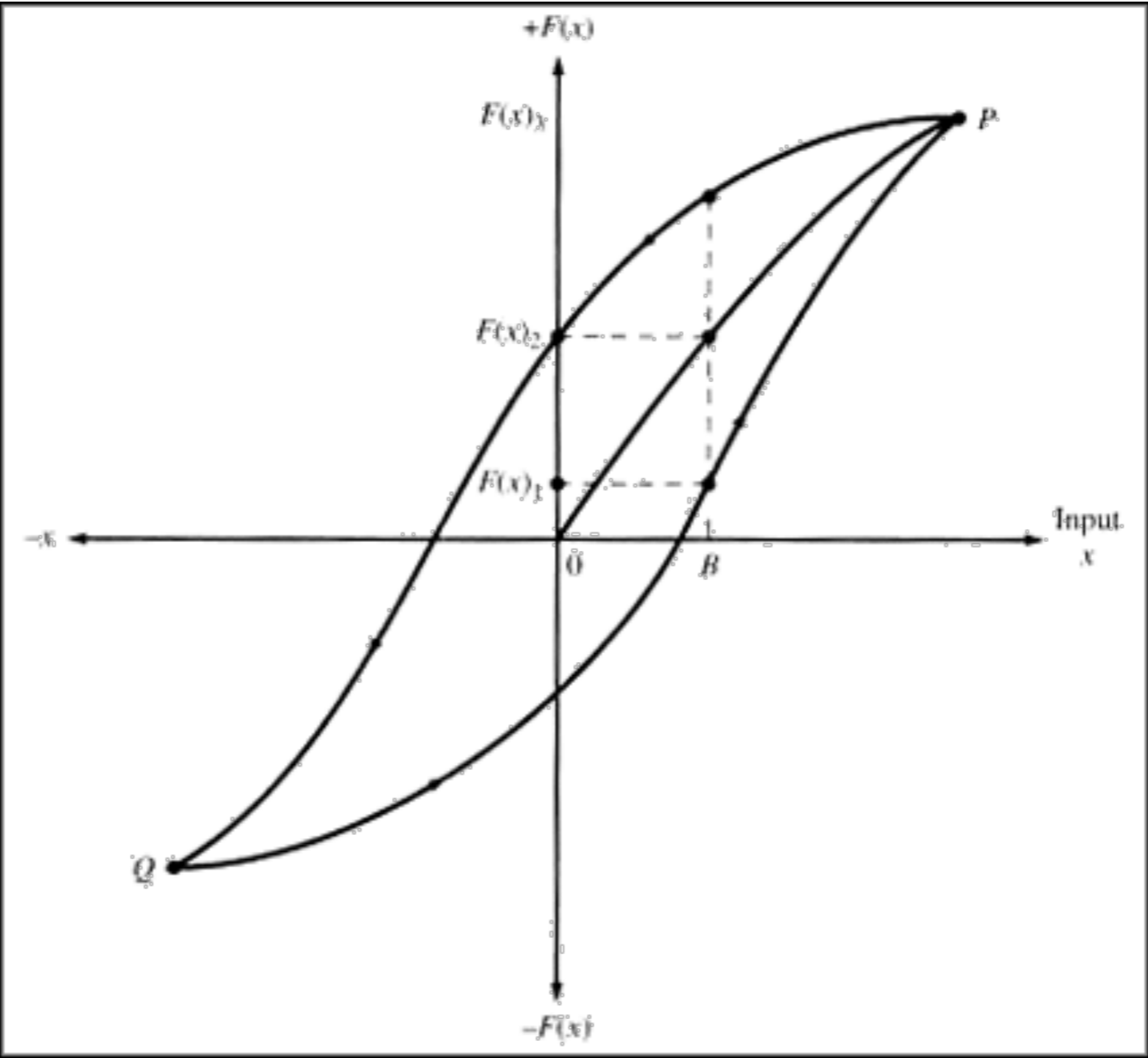
Integrated Signal Conditioning Devices



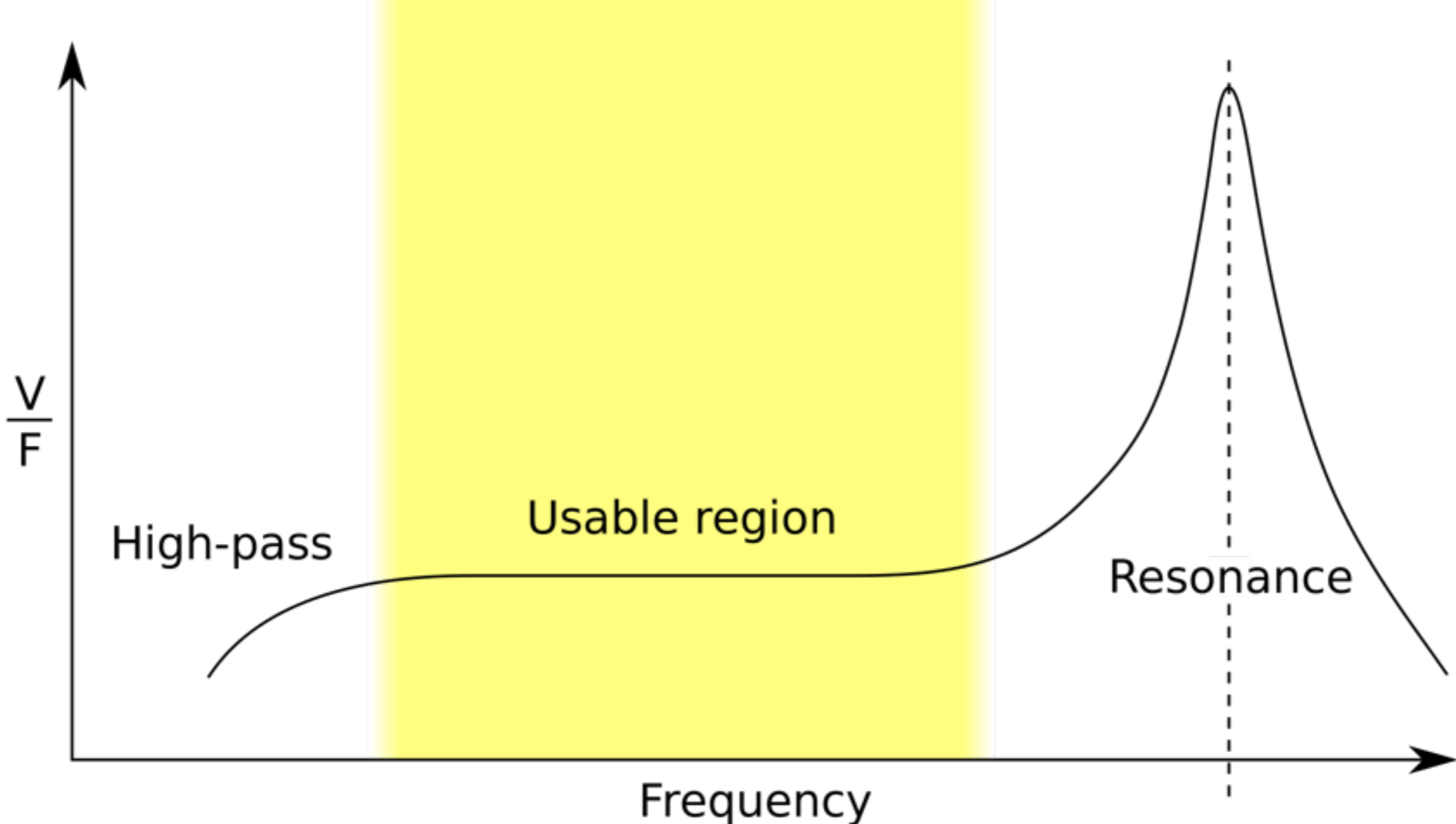
Offset refers to a DC bias is a given transducer's output



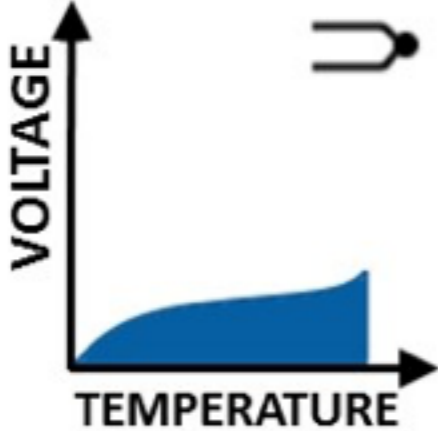
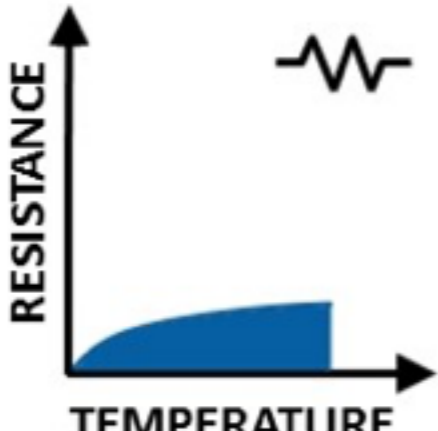
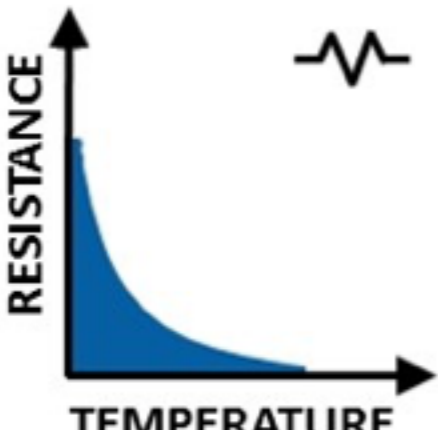
Hysteresis is the transducer's sensitivity to which direction (up/down) the physical quantity is changing



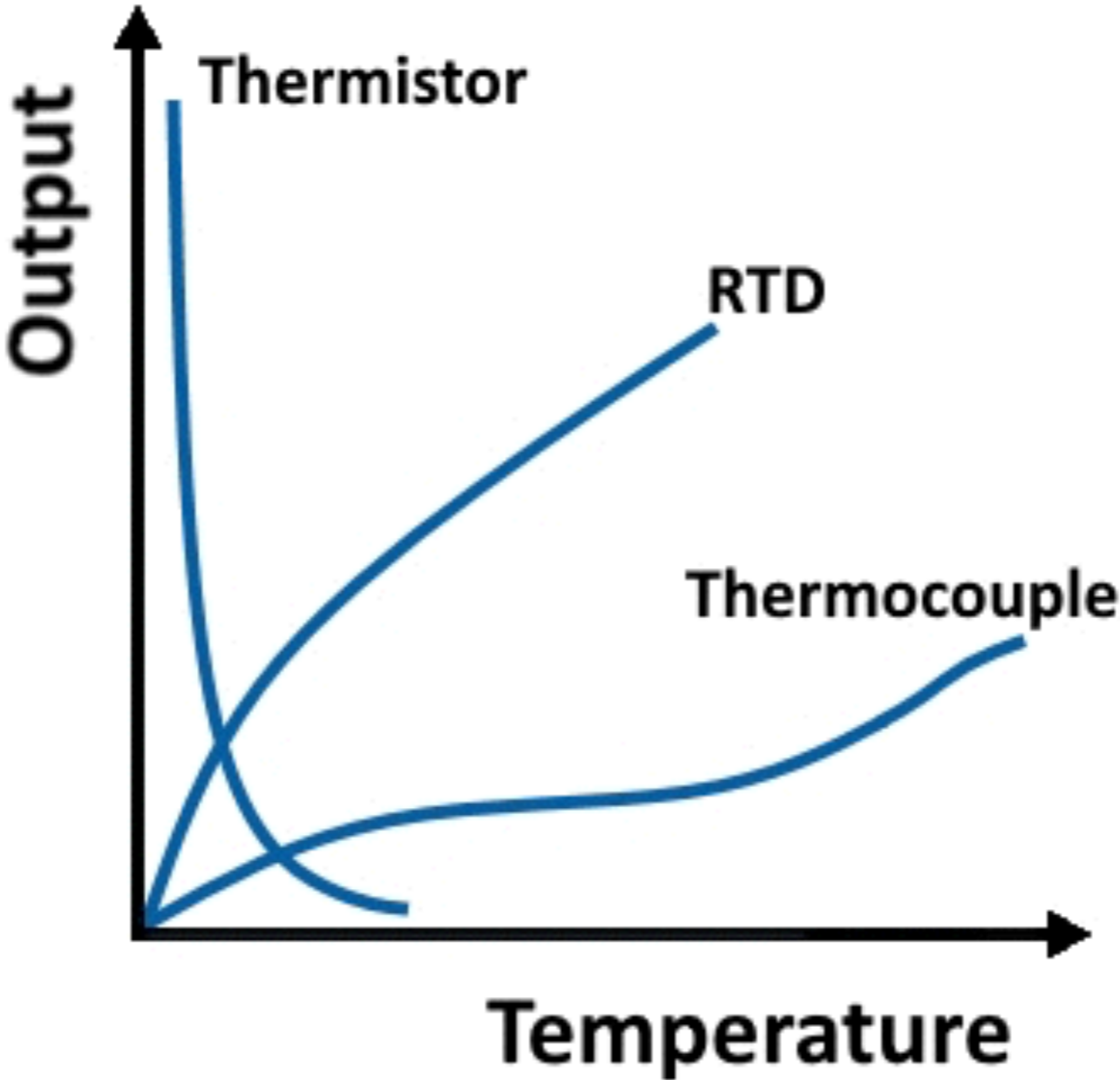
Dynamic linearity describes how well a transducer's output can follow a rapidly changing quantity



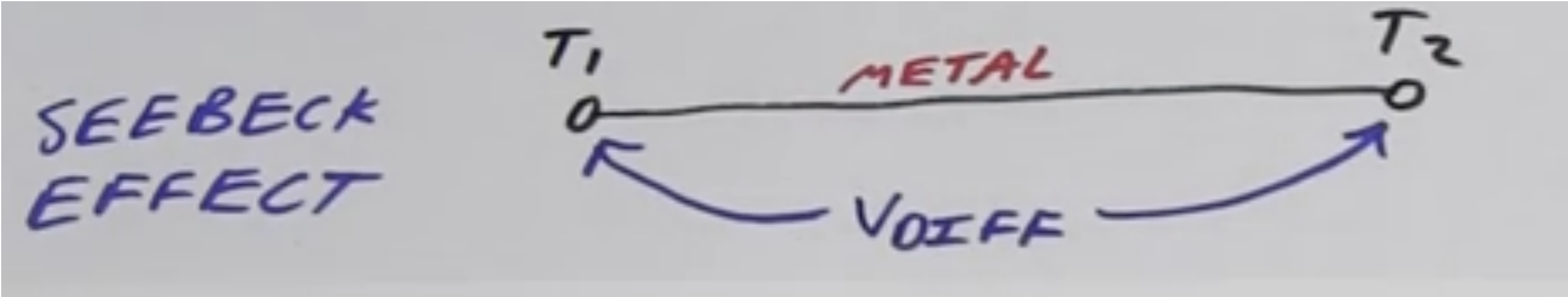
Temperature

	Advantages	Disadvantages
<p>THERMOCOUPLES</p> 	<ul style="list-style-type: none"> ✓ Simple ✓ Rugged ✓ Inexpensive ✓ No external power ✓ Wide temperature range ✓ Variety of styles 	<ul style="list-style-type: none"> × Nonlinear response × Small sensitivity × Small output voltage × Requires CJC × Least stable
<p>RTD</p> 	<ul style="list-style-type: none"> ✓ Most stable ✓ Good Linearity ✓ Most accurate 	<ul style="list-style-type: none"> × Low sensitivity × Externally powered × Costly × Small output resistance × Self-heating error
<p>THERMISTOR</p> 	<ul style="list-style-type: none"> ✓ Fast ✓ High output ✓ Minimal lead resistance error 	<ul style="list-style-type: none"> × Limited temperature range × Externally powered × Nonlinear × More fragile × Self-heating error

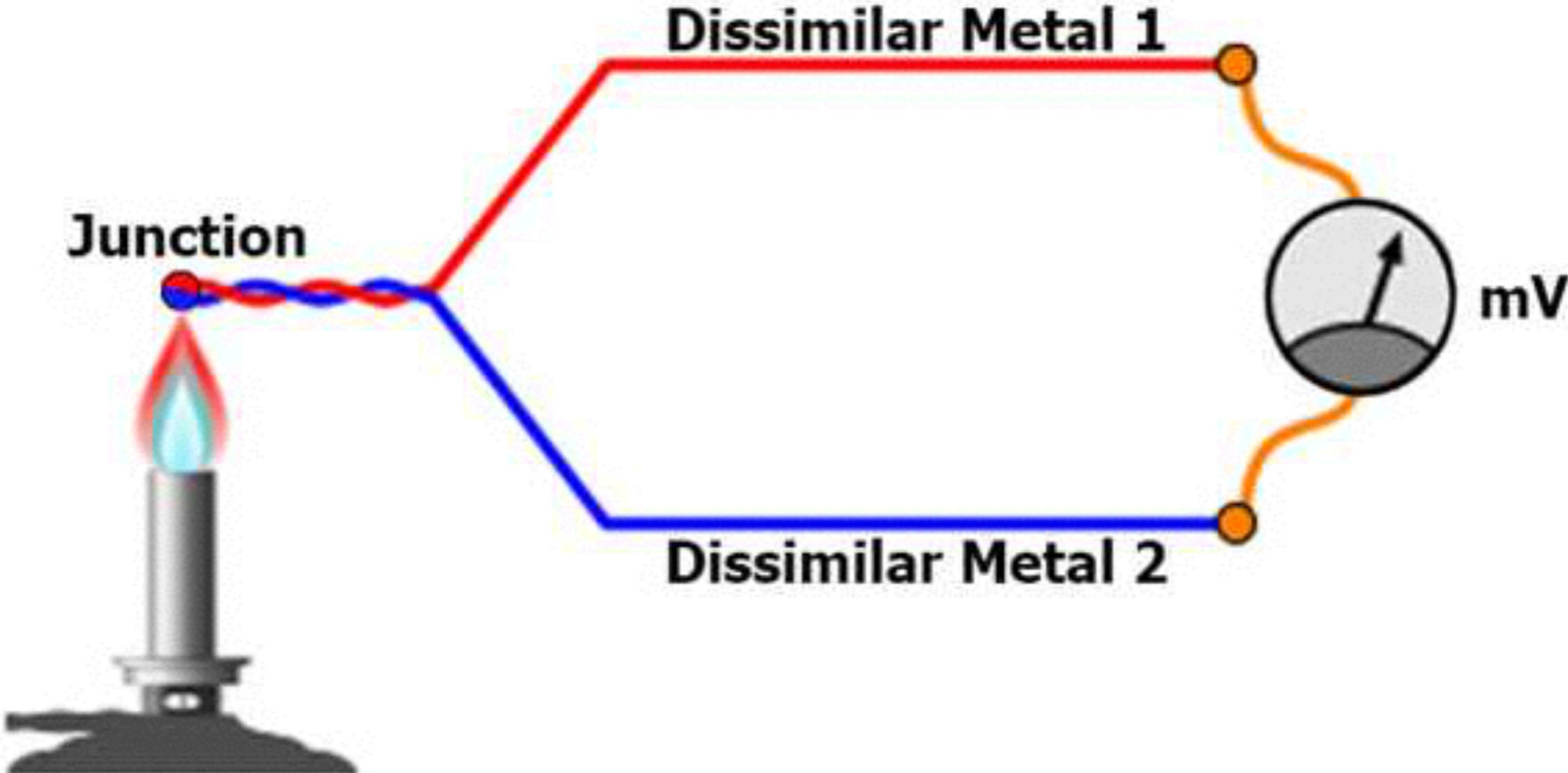
Each type of temperature sensor has a different output curve



Thermocouples work on a principle called the Seebeck effect



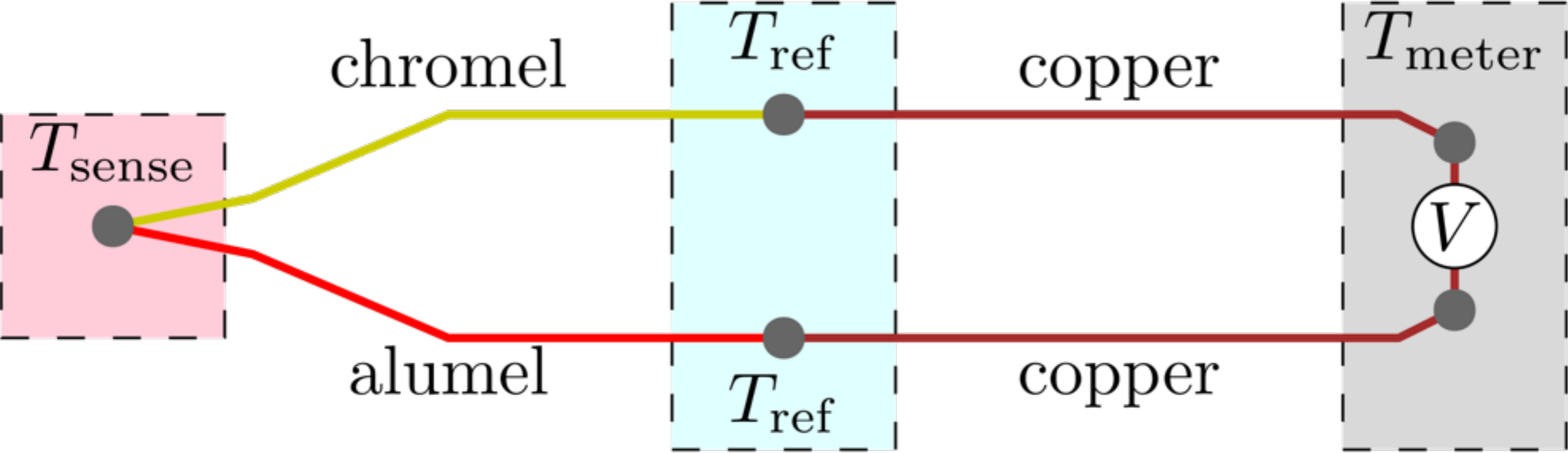
Two dissimilar metals are joined to make a transducer



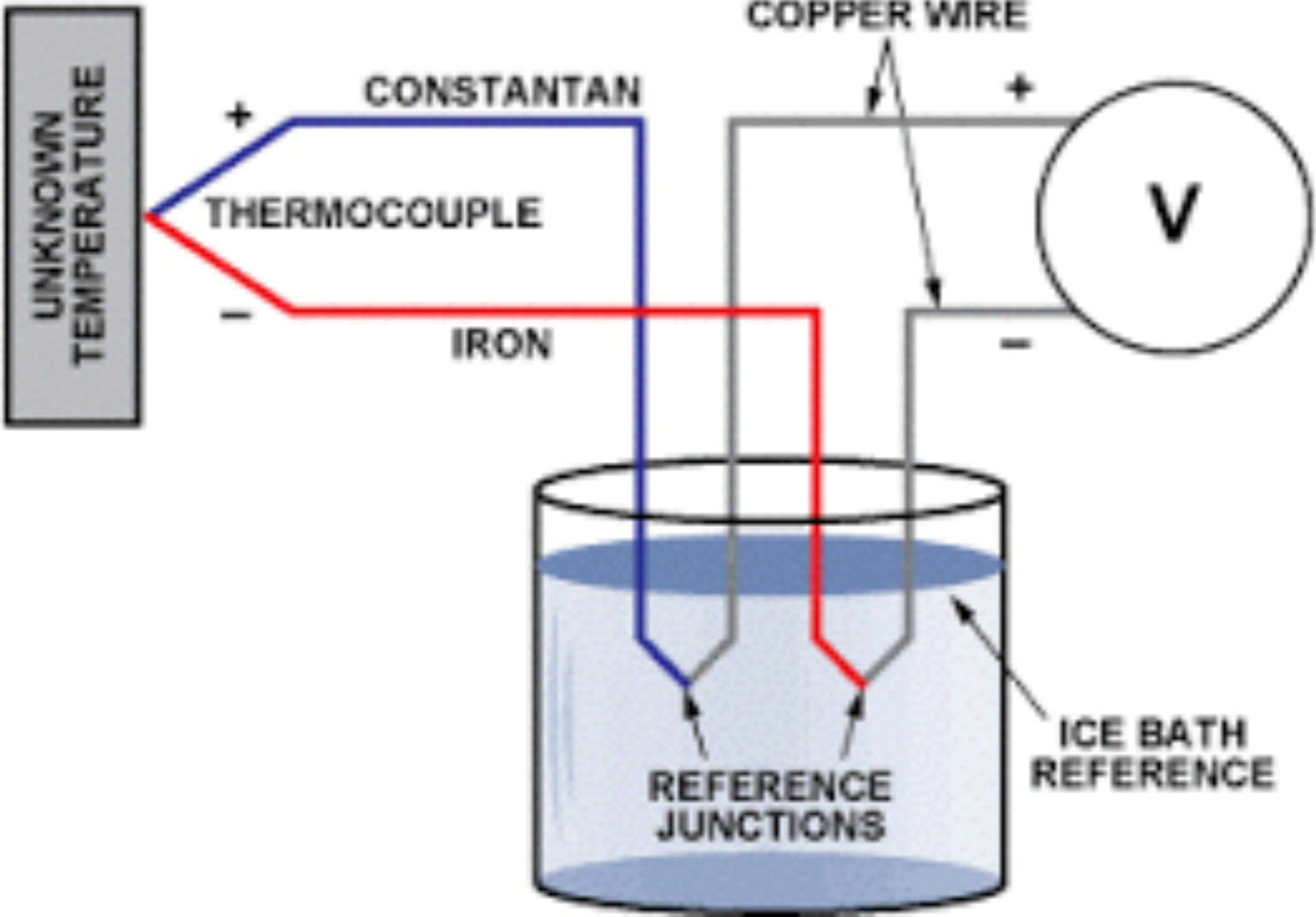
There are many metal combinations or types of thermocouples

Common Thermocouple Temperature Ranges			
Calibration	Temperature Range	Standard Limits of Error	Special Limits of Error
J	0° to 750°C (32° to 1382°F)	Greater of 2.2°C or 0.75%	Greater of 1.1°C or 0.4%
K	-200° to 1250°C (-328° to 2282°F)	Greater of 2.2°C or 0.75%	Greater of 1.1°C or 0.4%
E	-200° to 900°C (-328° to 1652°F)	Greater of 1.7°C or 0.5%	Greater of 1.0°C or 0.4%
T	-250° to 350°C (-328° to 662°F)	Greater of 1.0°C or 0.75%	Greater of 0.5°C or 0.4%

The challenge is unintentional junctions in the system



The challenge is unintentional junctions in the system



We measure the temperature of the “cold junction” and compensate for it with NIST tables

ITS-90 Table for type K thermocouple

°C	0	-1	-2	-3	-4	-5	-6	-7	-8	-9	-10
Thermoelectric Voltage in mV											
-270	-6.458										
-260	-6.441	-6.444	-6.446	-6.448	-6.450	-6.452	-6.453	-6.455	-6.456	-6.457	-6.458
-250	-6.404	-6.408	-6.413	-6.417	-6.421	-6.425	-6.429	-6.432	-6.435	-6.438	-6.441
-240	-6.344	-6.351	-6.358	-6.364	-6.370	-6.377	-6.382	-6.388	-6.393	-6.399	-6.404
-230	-6.262	-6.271	-6.280	-6.289	-6.297	-6.306	-6.314	-6.322	-6.329	-6.337	-6.344
-220	-6.158	-6.170	-6.181	-6.192	-6.202	-6.213	-6.223	-6.233	-6.243	-6.252	-6.262
-210	-6.035	-6.048	-6.061	-6.074	-6.087	-6.099	-6.111	-6.123	-6.135	-6.147	-6.158
-200	-5.891	-5.907	-5.922	-5.936	-5.951	-5.965	-5.980	-5.994	-6.007	-6.021	-6.035
-190	-5.730	-5.747	-5.763	-5.780	-5.797	-5.813	-5.829	-5.845	-5.861	-5.876	-5.891
-180	-5.550	-5.569	-5.588	-5.606	-5.624	-5.642	-5.660	-5.678	-5.695	-5.713	-5.730
-170	-5.354	-5.374	-5.395	-5.415	-5.435	-5.454	-5.474	-5.493	-5.512	-5.531	-5.550
-160	-5.141	-5.163	-5.185	-5.207	-5.228	-5.250	-5.271	-5.292	-5.313	-5.333	-5.354
-150	-4.913	-4.936	-4.960	-4.983	-5.006	-5.029	-5.052	-5.074	-5.097	-5.119	-5.141
-140	-4.669	-4.694	-4.719	-4.744	-4.768	-4.793	-4.817	-4.841	-4.865	-4.889	-4.913
-130	-4.411	-4.437	-4.463	-4.490	-4.516	-4.542	-4.567	-4.593	-4.618	-4.644	-4.669
-120	-4.138	-4.166	-4.194	-4.221	-4.249	-4.276	-4.303	-4.330	-4.357	-4.384	-4.411
-110	-3.852	-3.882	-3.911	-3.939	-3.968	-3.997	-4.025	-4.054	-4.082	-4.110	-4.138
-100	-3.554	-3.584	-3.614	-3.645	-3.675	-3.705	-3.734	-3.764	-3.794	-3.823	-3.852
-90	-3.243	-3.274	-3.306	-3.337	-3.368	-3.400	-3.431	-3.462	-3.492	-3.523	-3.554
-80	-2.920	-2.953	-2.986	-3.018	-3.050	-3.083	-3.115	-3.147	-3.179	-3.211	-3.243
-70	-2.587	-2.620	-2.654	-2.688	-2.721	-2.755	-2.788	-2.821	-2.854	-2.887	-2.920
-60	-2.243	-2.278	-2.312	-2.347	-2.382	-2.416	-2.450	-2.485	-2.519	-2.553	-2.587
-50	-1.889	-1.925	-1.961	-1.996	-2.032	-2.067	-2.103	-2.138	-2.173	-2.208	-2.243
-40	-1.527	-1.564	-1.600	-1.637	-1.673	-1.709	-1.745	-1.782	-1.818	-1.854	-1.889
-30	-1.156	-1.194	-1.231	-1.268	-1.305	-1.343	-1.380	-1.417	-1.453	-1.490	-1.527
-20	-0.778	-0.816	-0.854	-0.892	-0.930	-0.968	-1.006	-1.043	-1.081	-1.119	-1.156
-10	-0.392	-0.431	-0.470	-0.508	-0.547	-0.586	-0.624	-0.663	-0.701	-0.739	-0.778
0	0.000	-0.039	-0.079	-0.118	-0.157	-0.197	-0.236	-0.275	-0.314	-0.353	-0.392
°C	0	-1	-2	-3	-4	-5	-6	-7	-8	-9	-10

Or use a high order polynomial fit

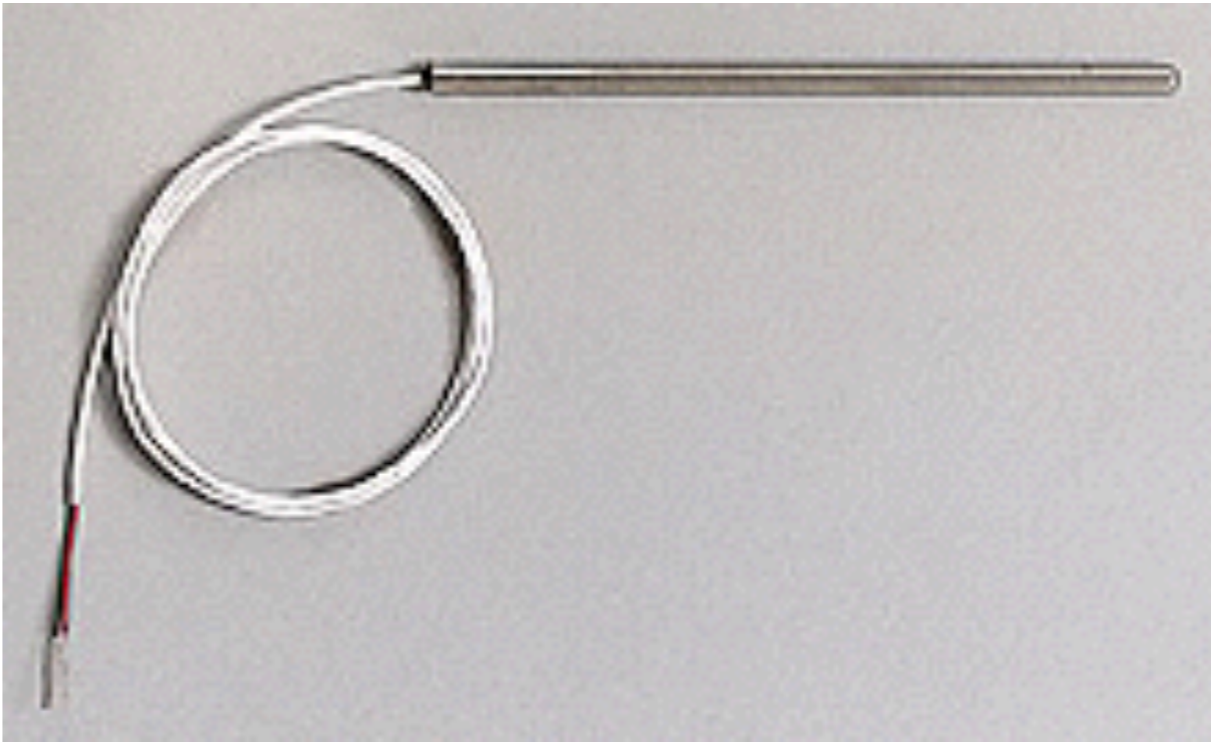
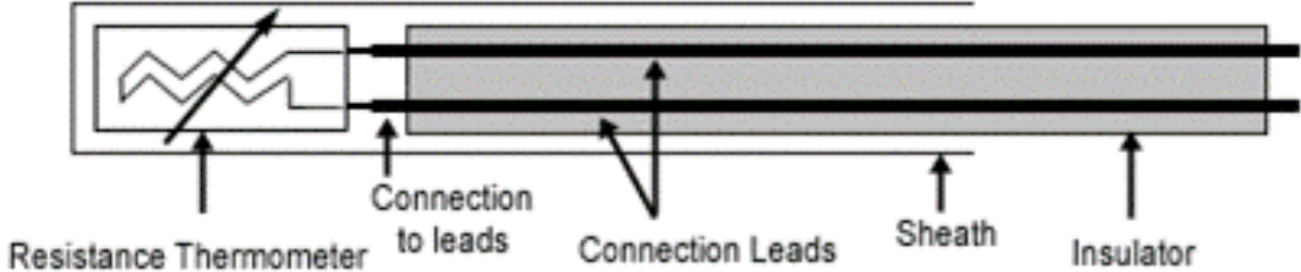
Type K Thermocouples - coefficients of approximate inverse functions giving temperature, t_{90} , as a function of the thermoelectric voltage, E , in selected temperature and voltage ranges. The functions are of the form:

$$t_{90} = c_0 + c_1E + c_2E^2 + \dots + c_iE^i$$

where E is in microvolts and t_{90} is in degrees Celsius.

Temperature Range:	-200 to 0°C	0 to 500°C	500 to 1,372°C
Voltage Range:	-5891 to 0 μV	0 to 20,644 μV	20,644 to 54,886 μV
$C_0 =$	0.000 000 0	0.000 000	-1.318 058 x 10 ²
$C_1 =$	2.517 346 2 x 10 ⁻²	2.508 355 x 10 ⁻²	4.830 222 x 10 ⁻²
$C_2 =$	-1.166 287 8 x 10 ⁻⁶	7.860 106 x 10 ⁻⁸	-1.646 031 x 10 ⁻⁶
$C_3 =$	-1.083 363 8 x 10 ⁻⁹	-2.503 131 x 10 ⁻¹⁰	5.464 731 x 10 ⁻¹¹
$C_4 =$	-8.977 354 0 x 10 ⁻¹³	8.315 270 x 10 ⁻¹⁴	-9.650 715 x 10 ⁻¹⁶
$C_5 =$	-3.734 237 7 x 10 ⁻¹⁶	-1.228 034 x 10 ⁻¹⁷	8.802 193 x 10 ⁻²¹
$C_6 =$	-8.663 264 3 x 10 ⁻²⁰	9.804 036 x 10 ⁻²²	-3.110 810 x 10 ⁻²⁶
$C_7 =$	-1.045 059 8 x 10 ⁻²³	-4.413 030 x 10 ⁻²⁶	
$C_8 =$	-5.192 057 7 x 10 ⁻²⁸	1.057 734 x 10 ⁻³⁰	
$C_9 =$		-1.052 755 x 10 ⁻³⁵	
Error Range:	0.04°C to -0.02°C	0.04°C to -0.05°C	0.06°C to -0.05°C

RTDs change resistance based on the temperature



Multiple signal conditioning strategies can be used depending on the requirements and cost tradeoff

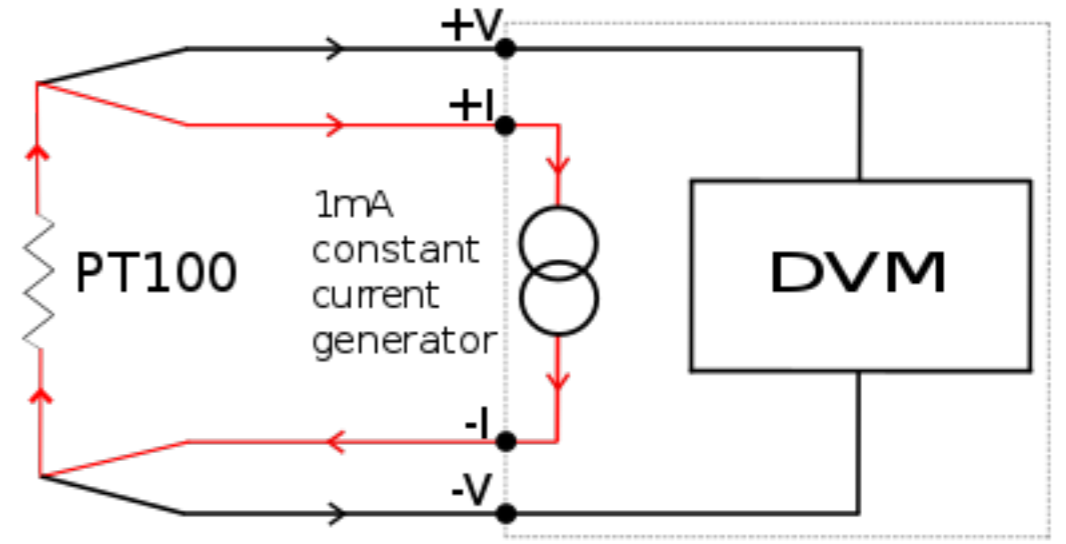
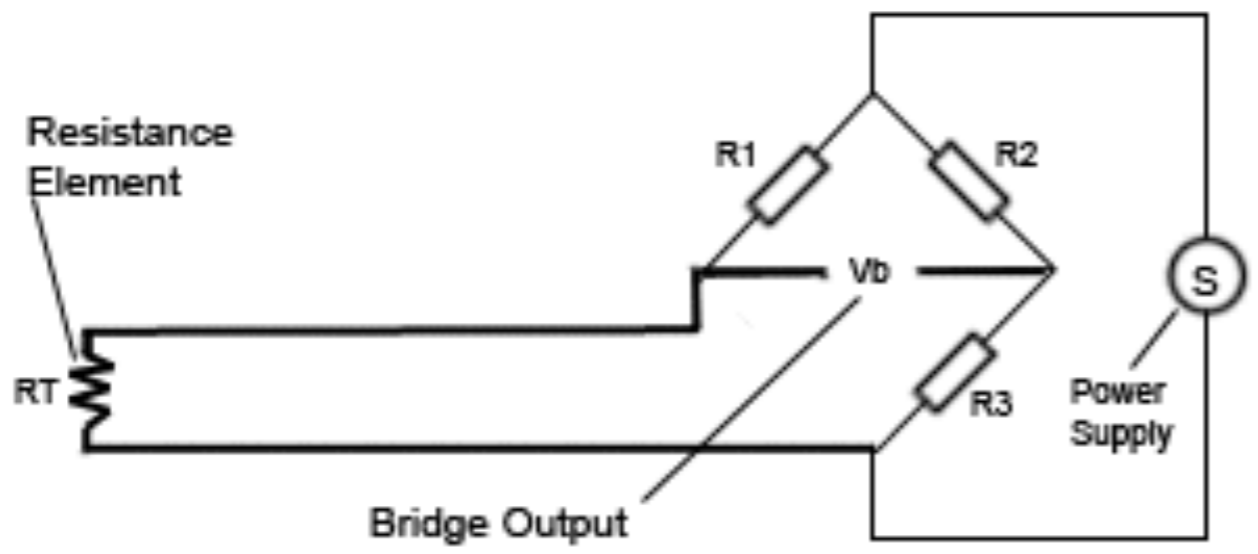
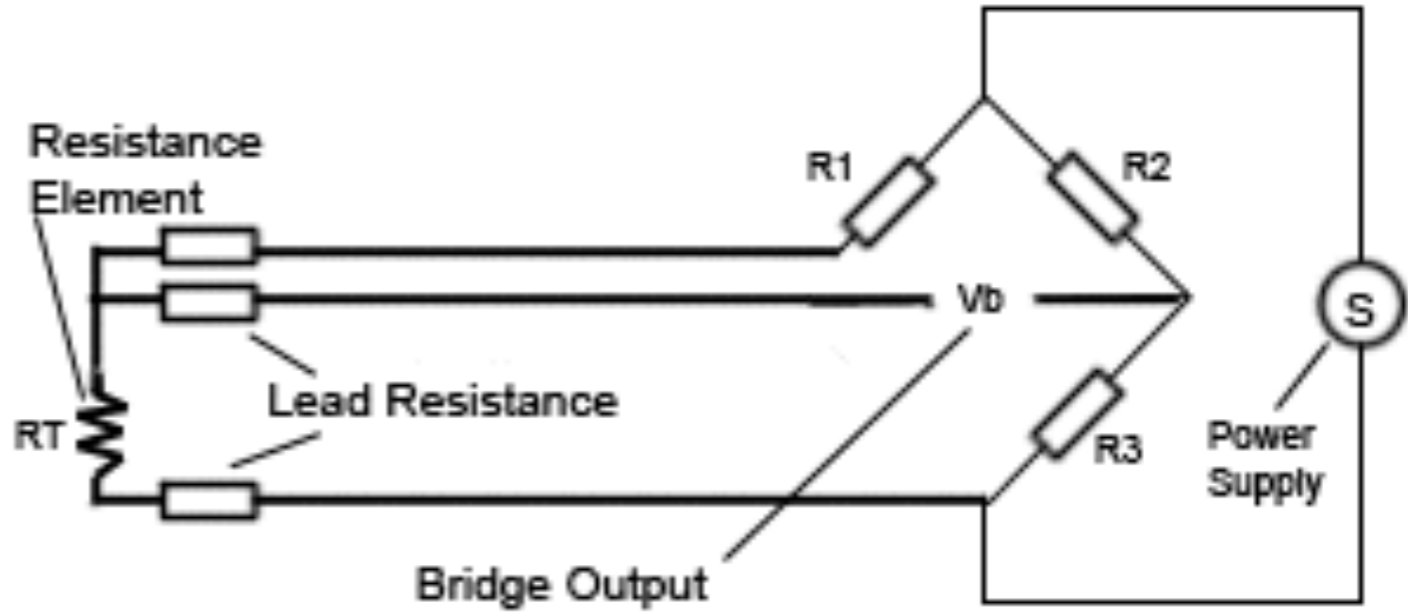


Image: Wikipedia

Thermistors also change their resistance with temperature

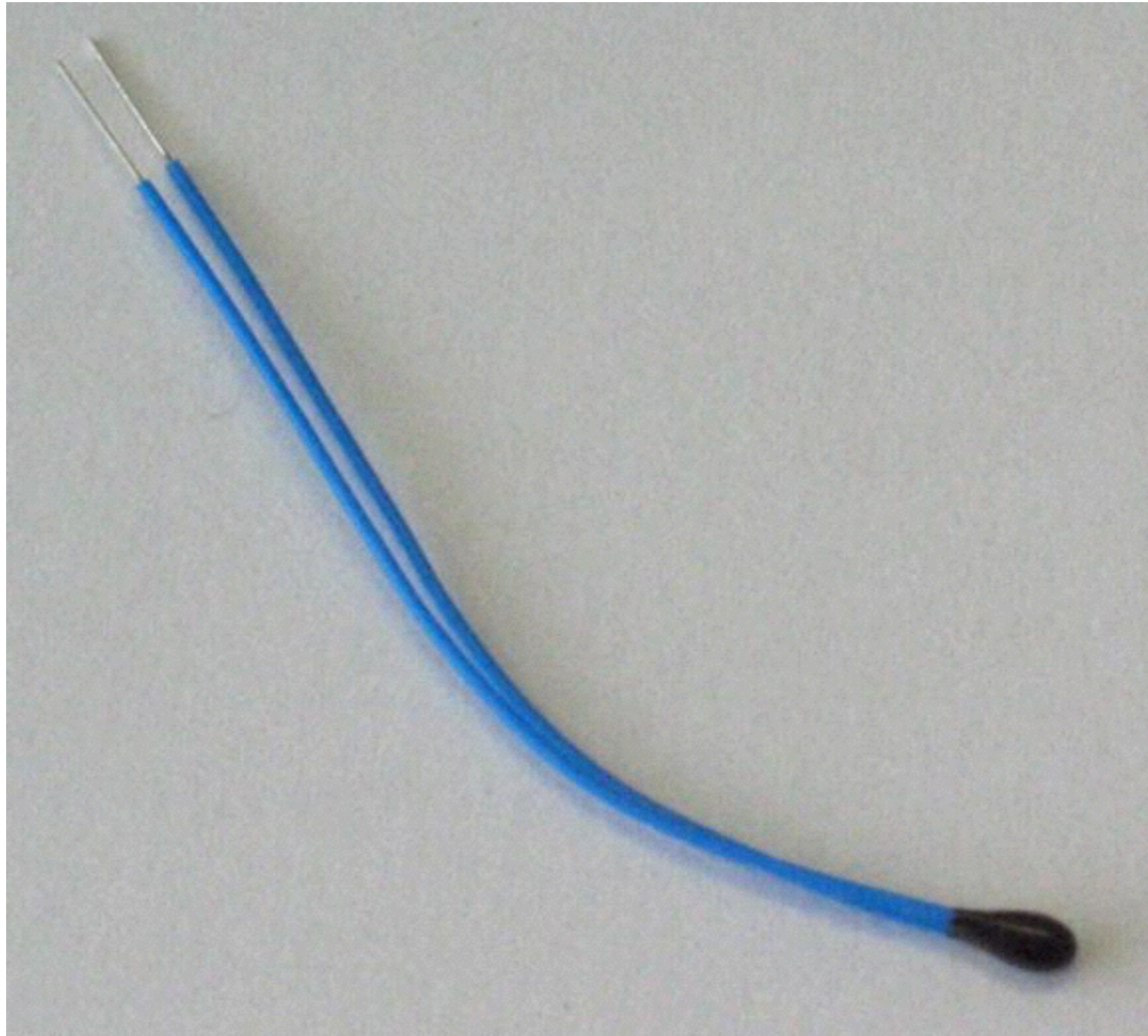
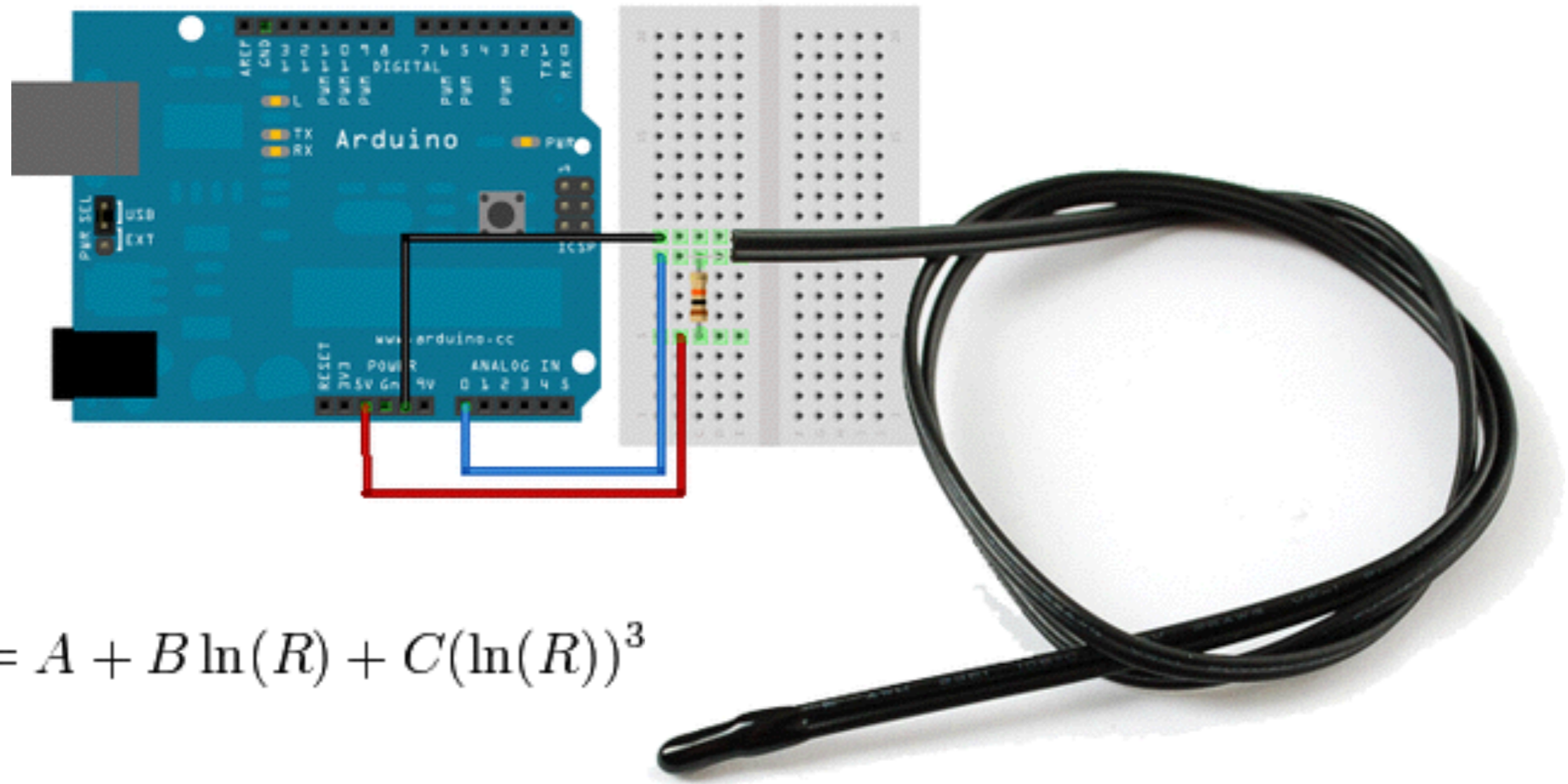


Image: Wikipedia

Conditioning happens with various resistor bridge/divider circuits



$$\frac{1}{T} = A + B \ln(R) + C(\ln(R))^3$$

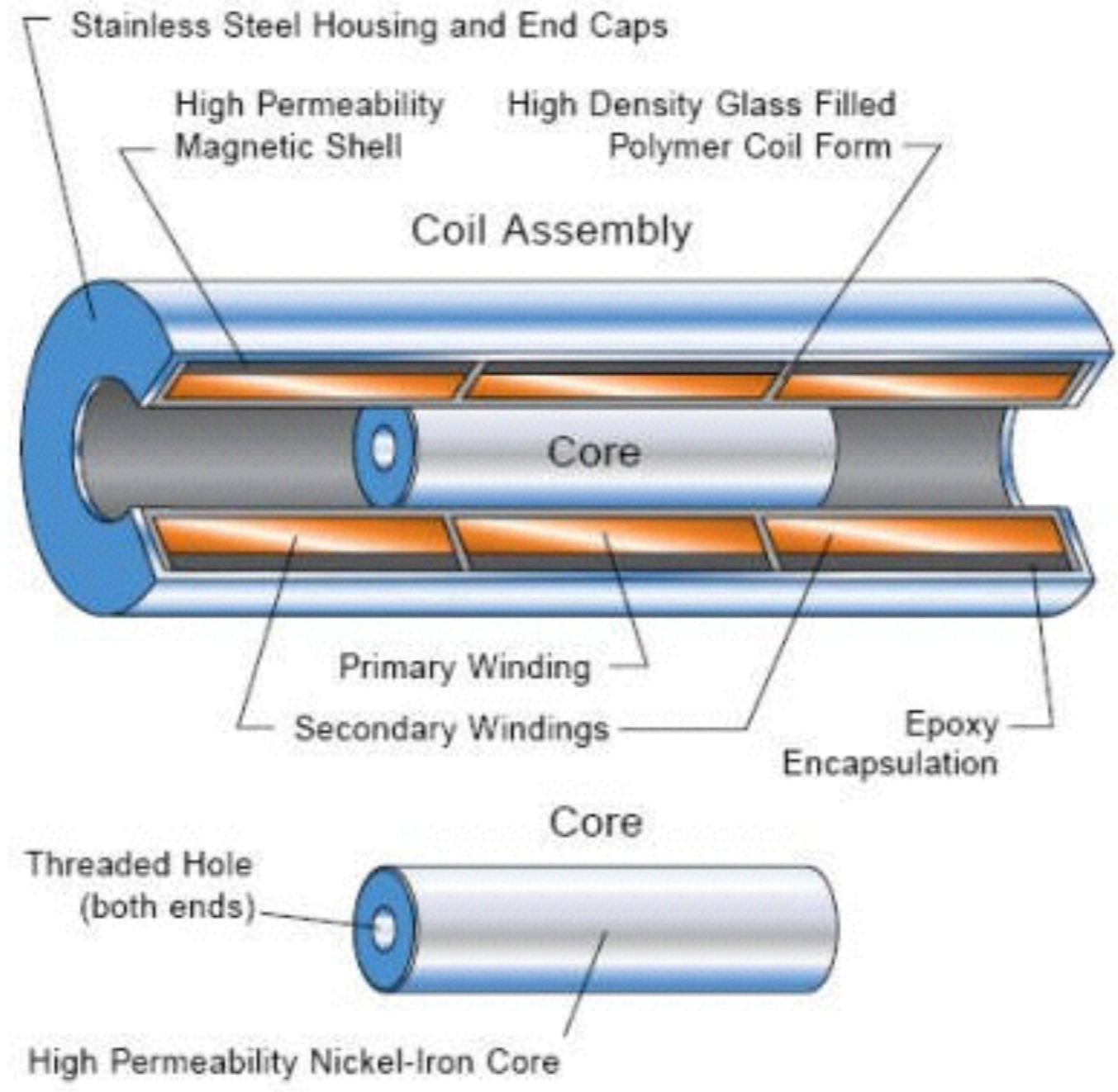
$$\frac{1}{T} = \frac{1}{T_0} + \frac{1}{B} \ln\left(\frac{R}{R_0}\right)$$

Displacement

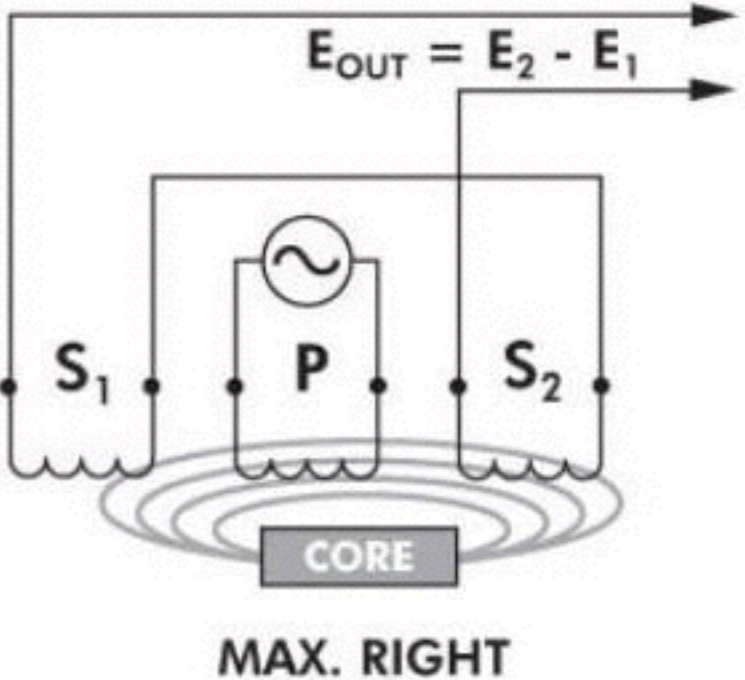
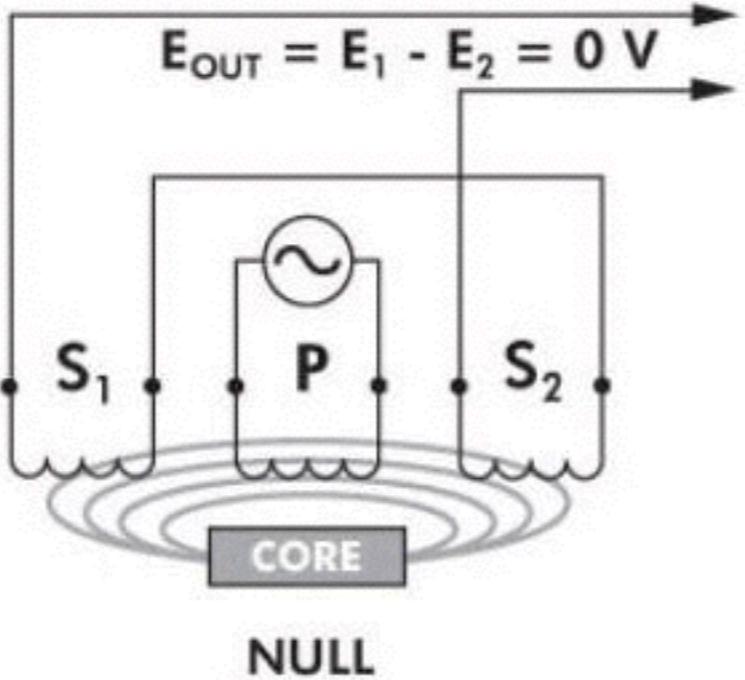
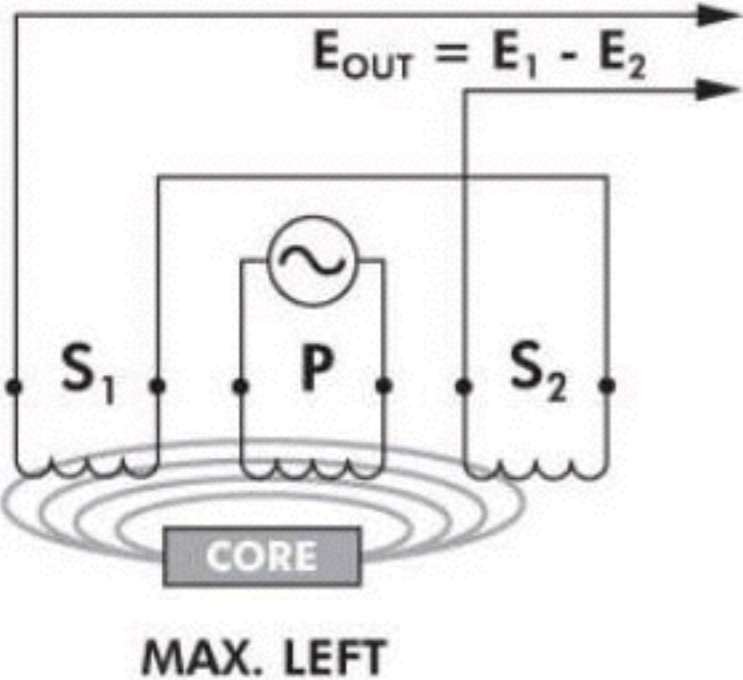
Displacement measurements can be performed in absolute or relative ways with a WIDE variety of transducers



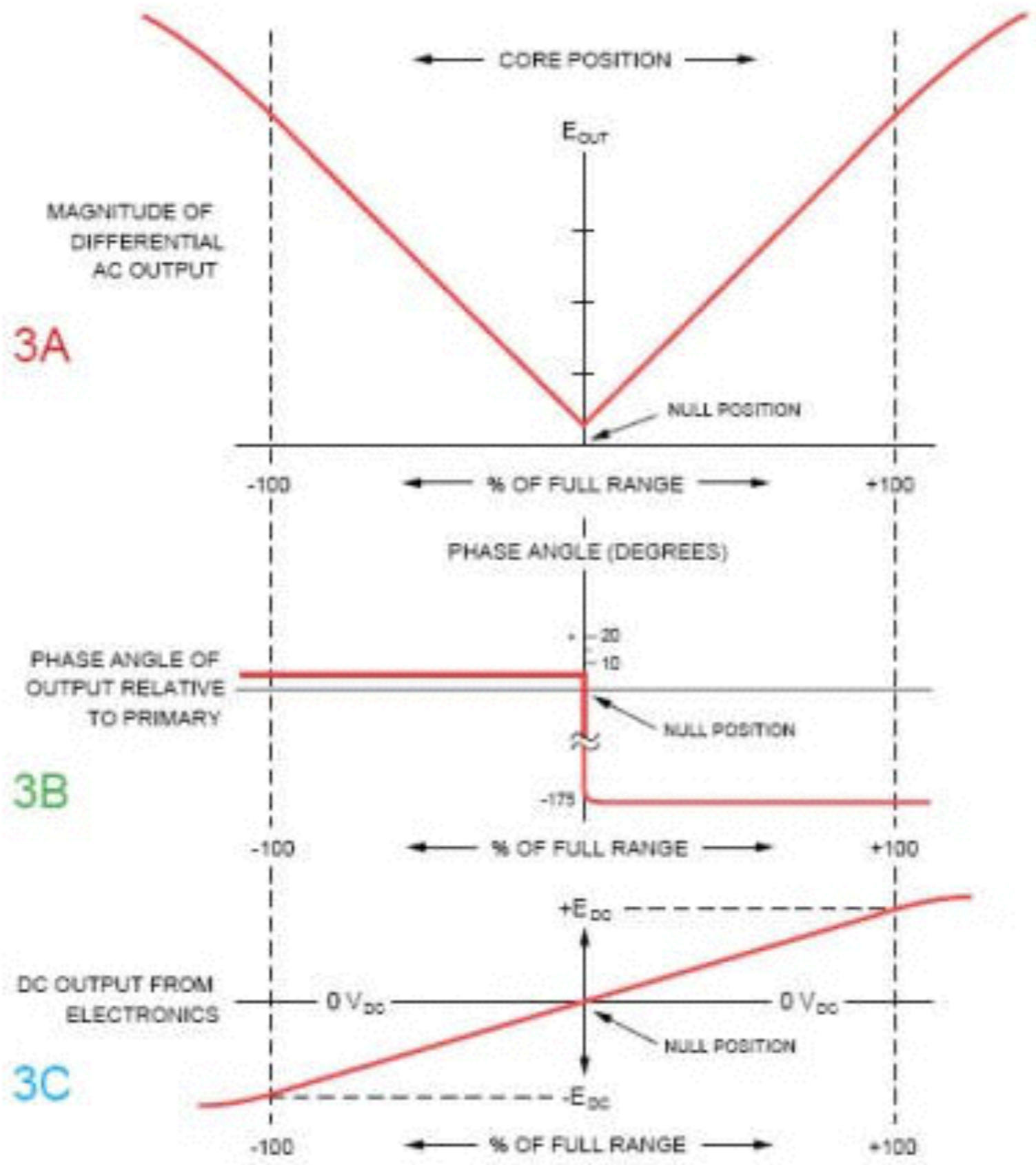
DCDTs/LVDTs are a differential transformer



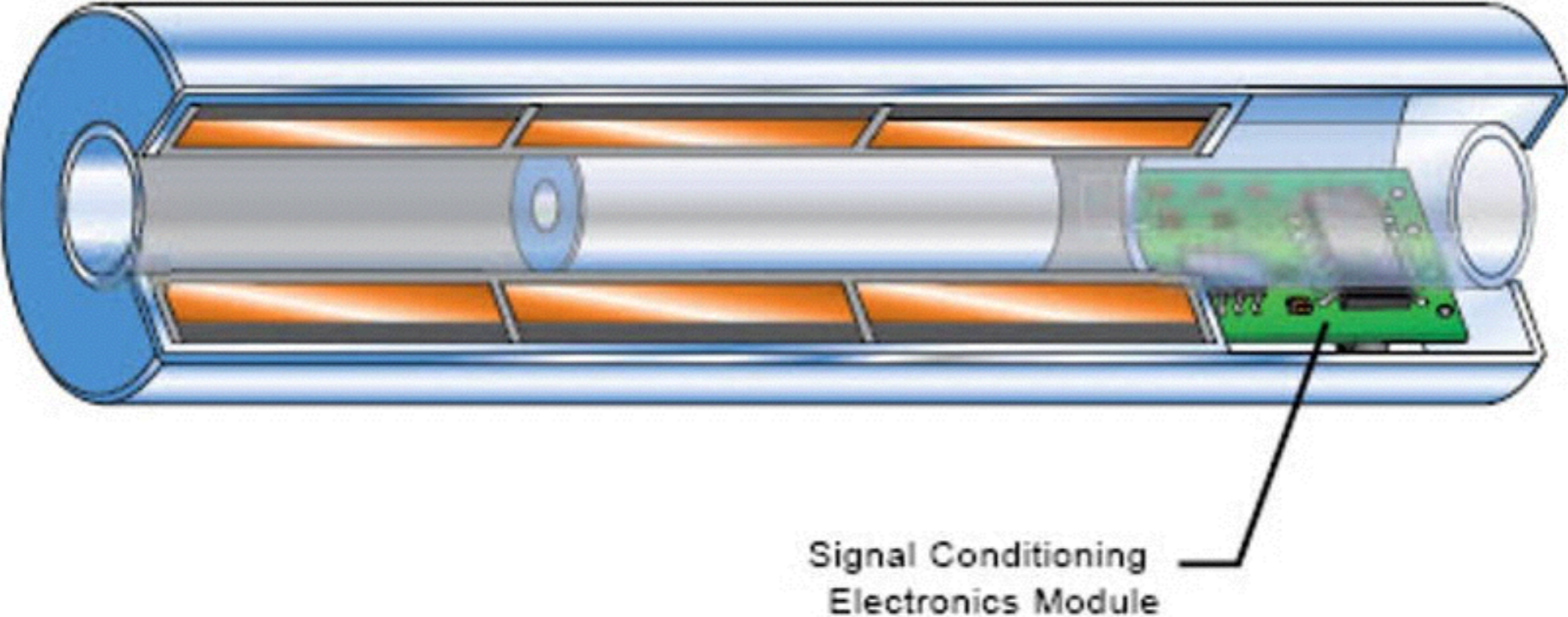
DCDTs/LVDTs are a differential transformer



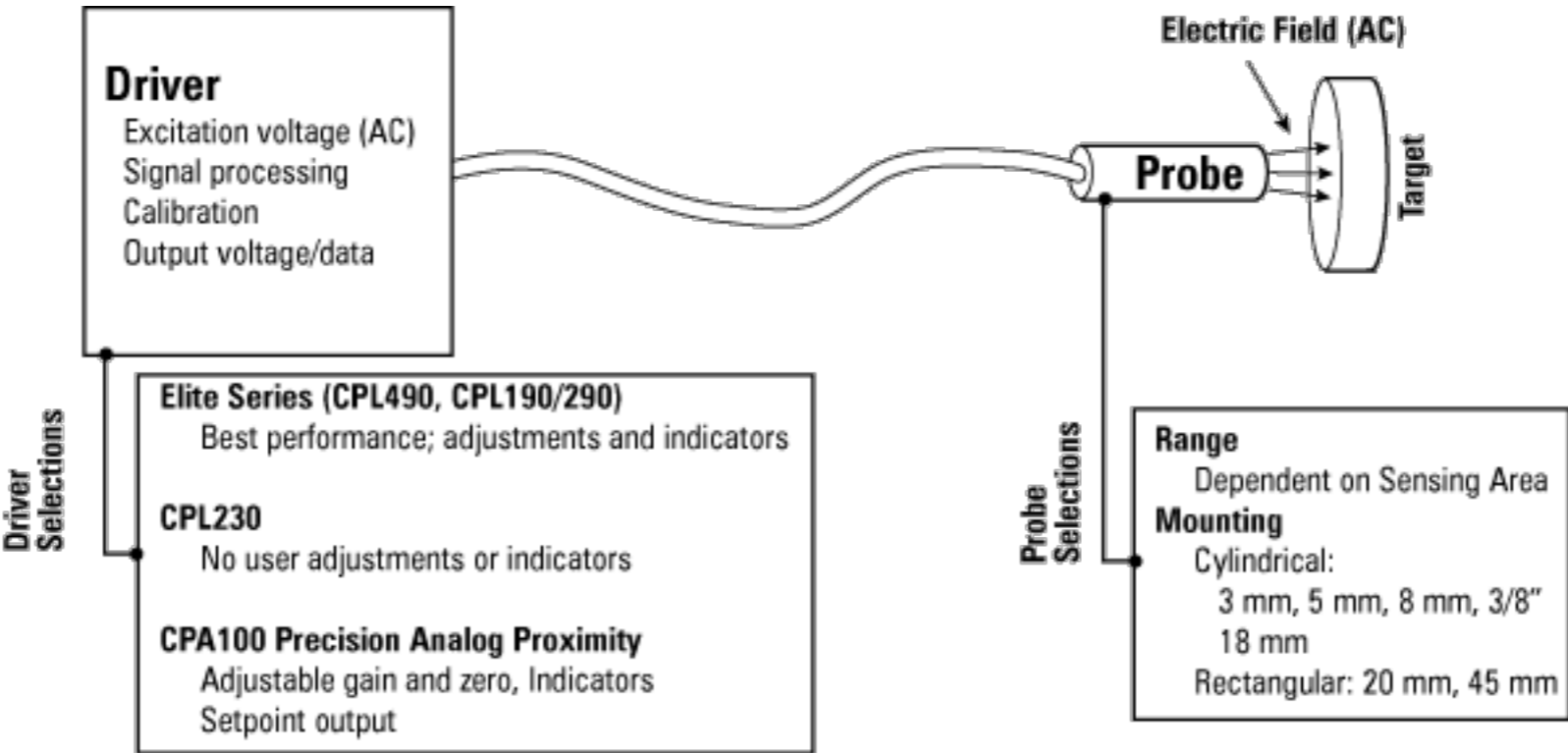
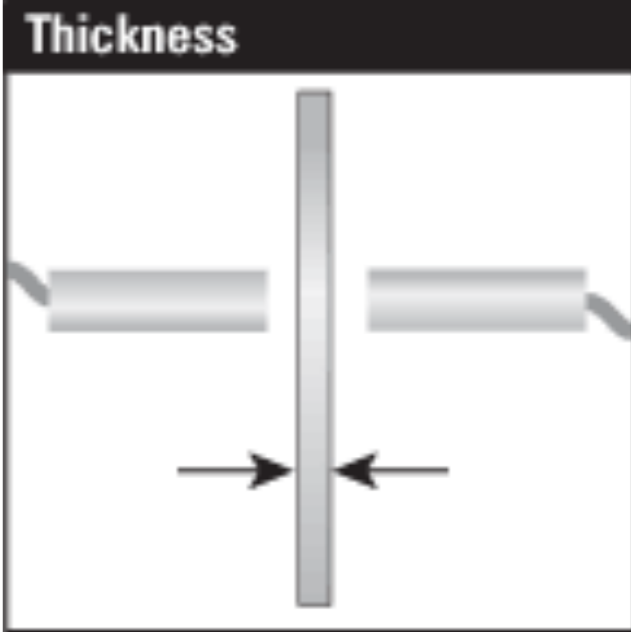
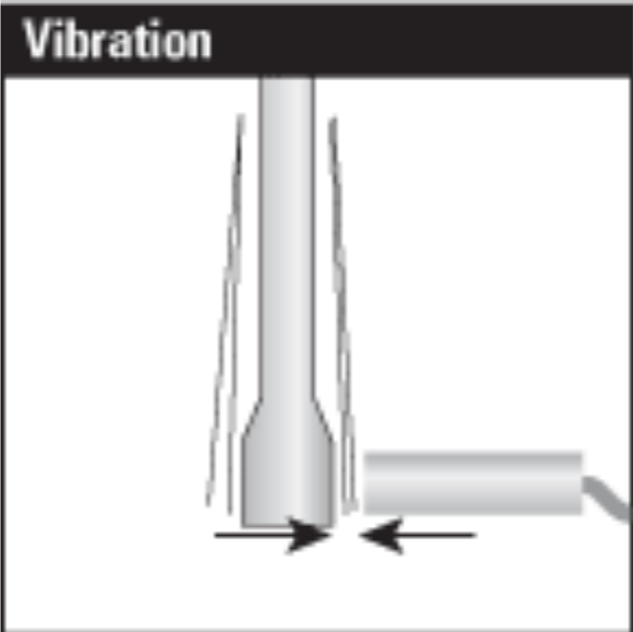
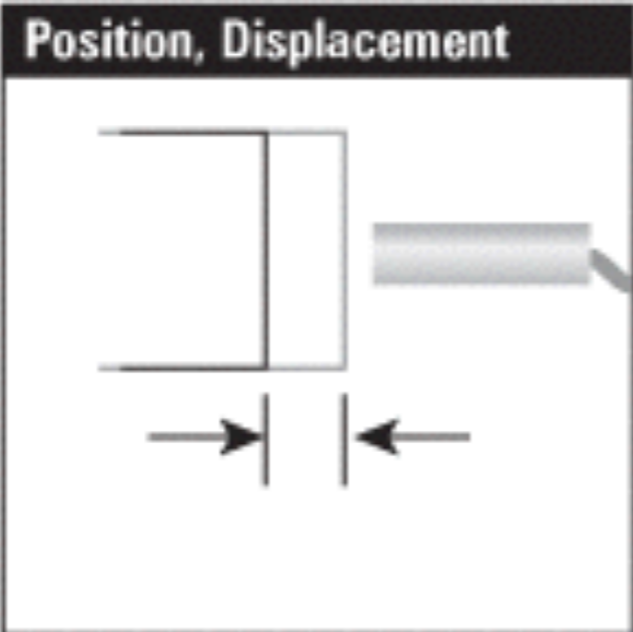
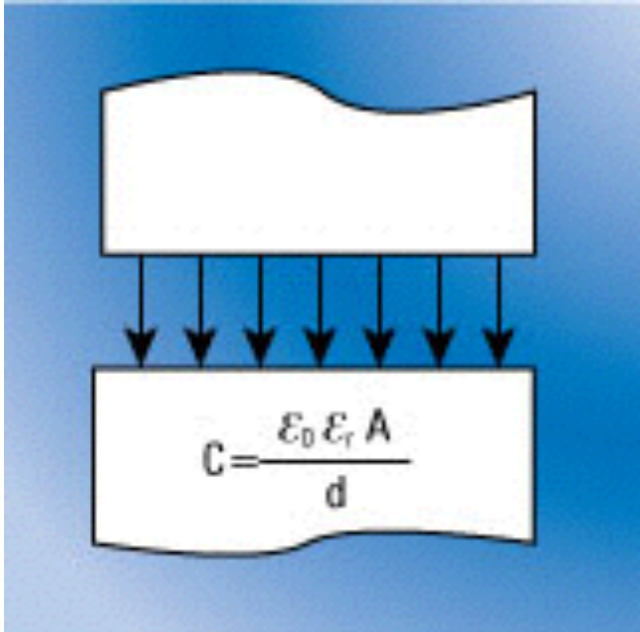
DCDTs/LVDTs are a differential transformer



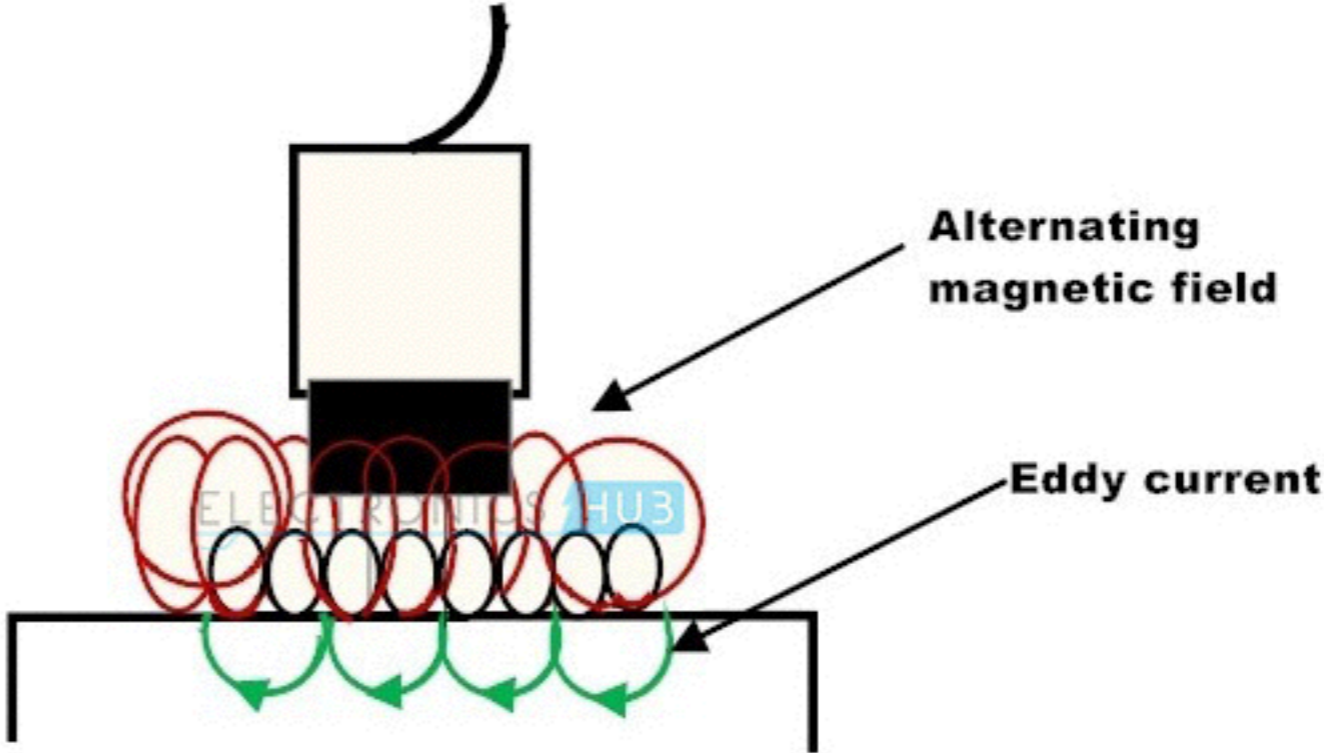
DCDTs include all of the necessary driving/conditioning electronics



Capacitive displacement sensors are very low noise and high resolution



Eddy current sensors are less expensive and still relatively low noise

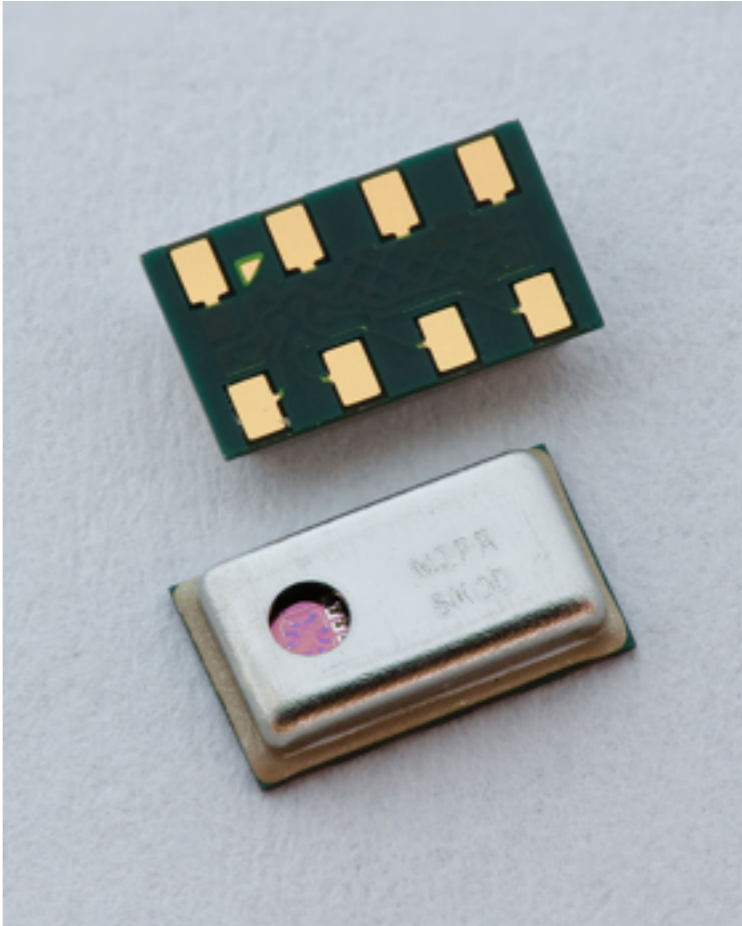
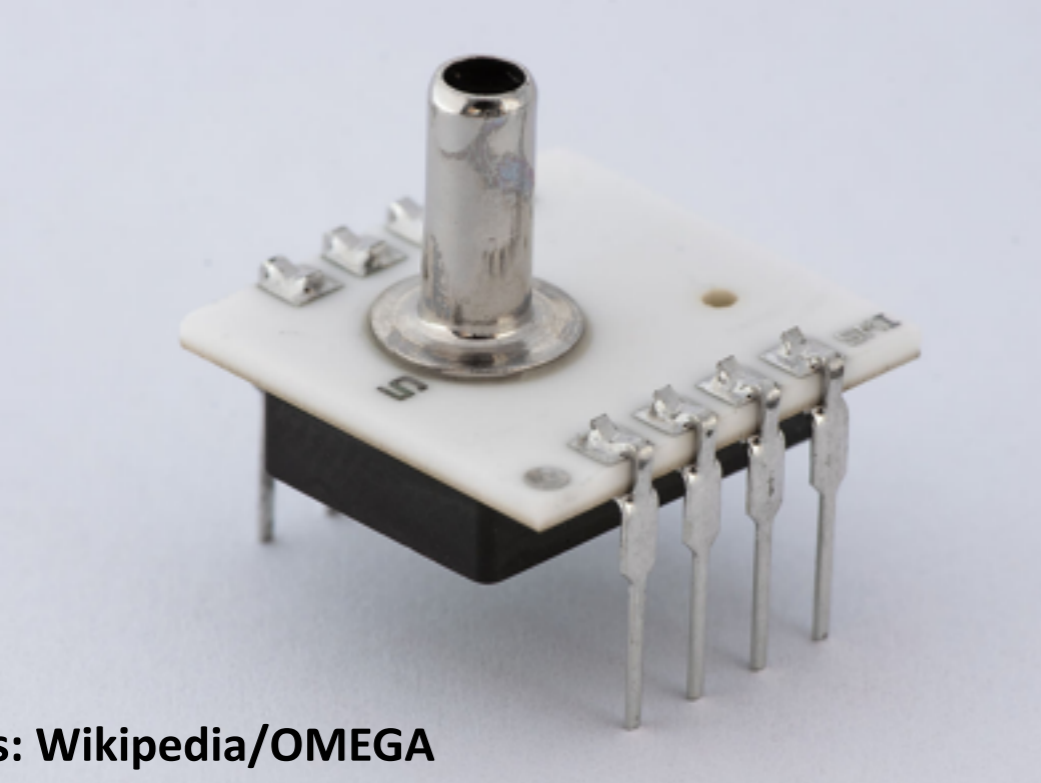


Pressure

Pressure transducers come in several types

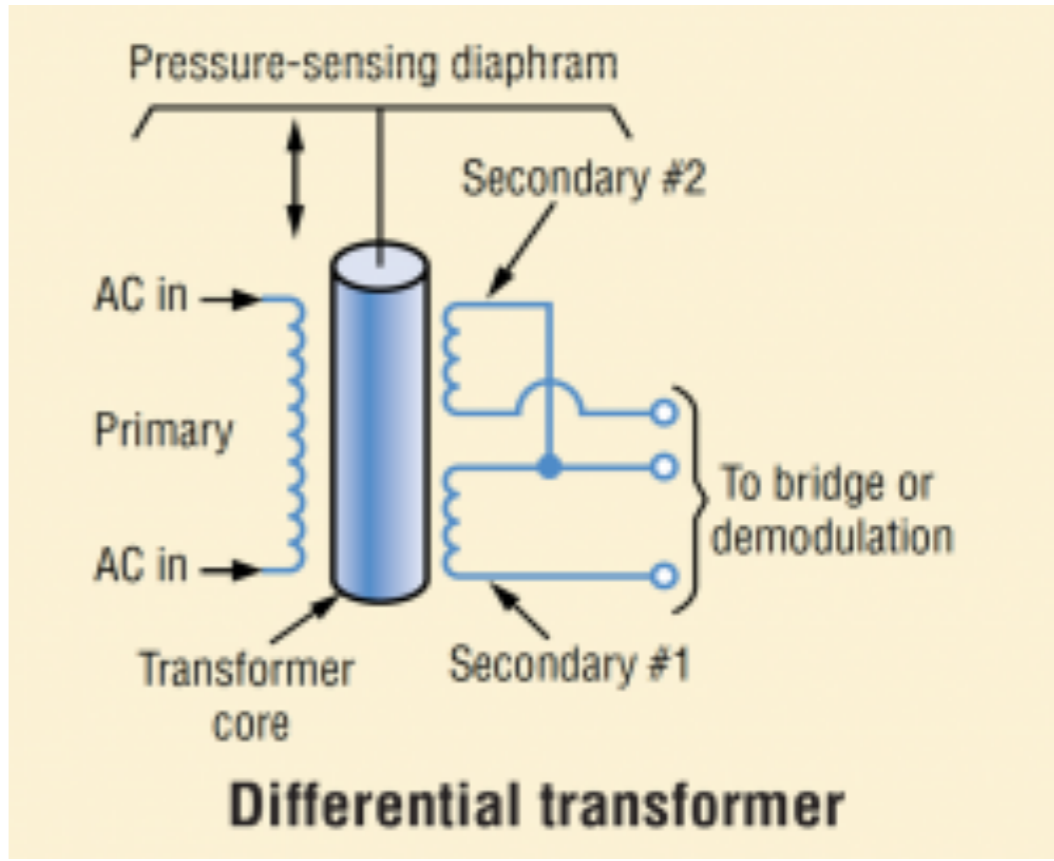
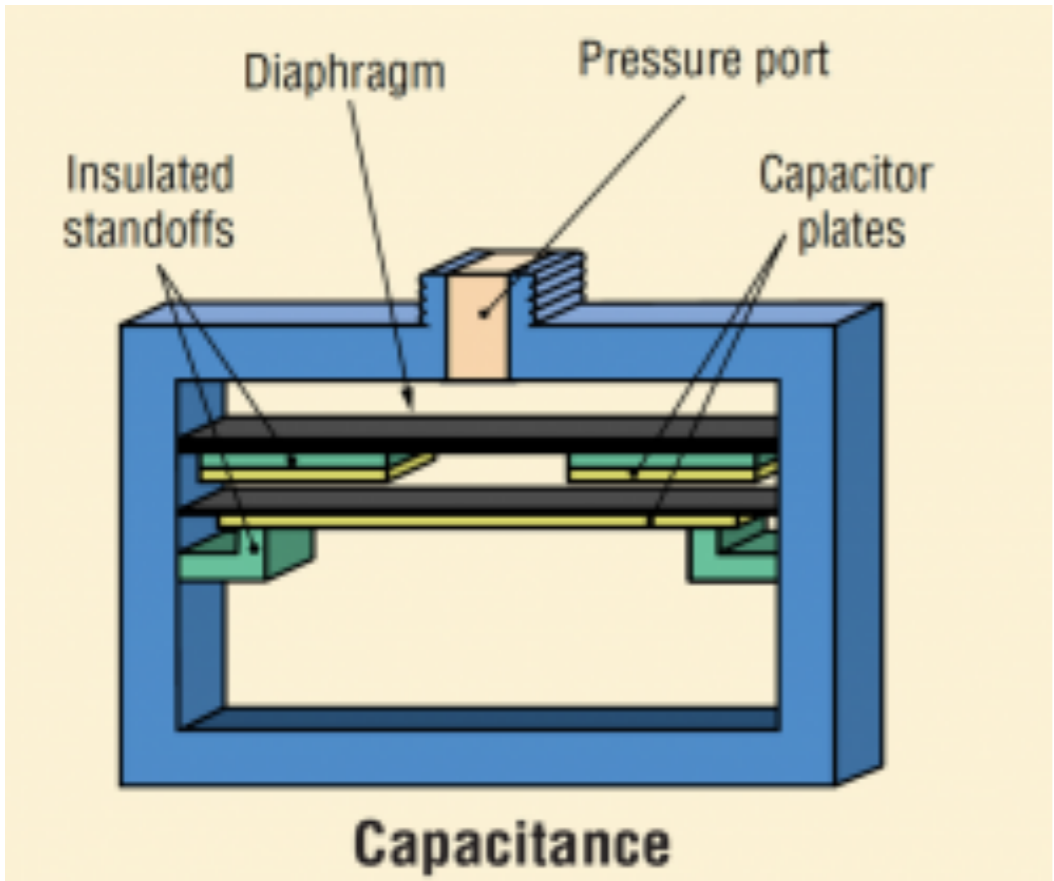
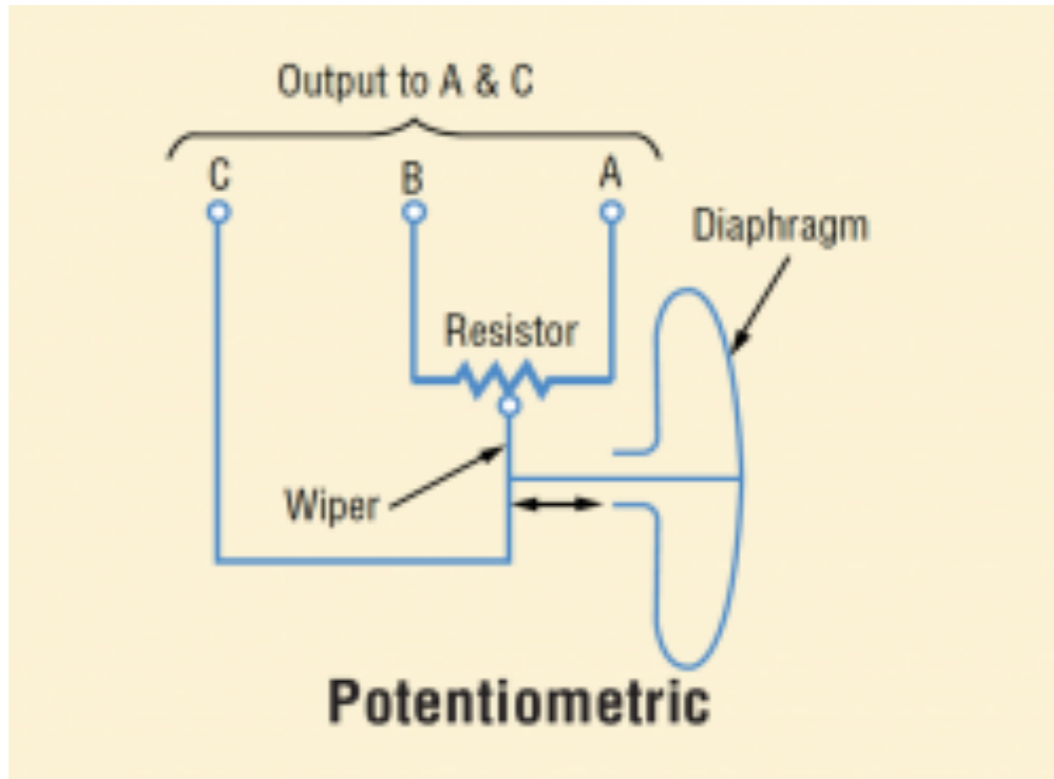
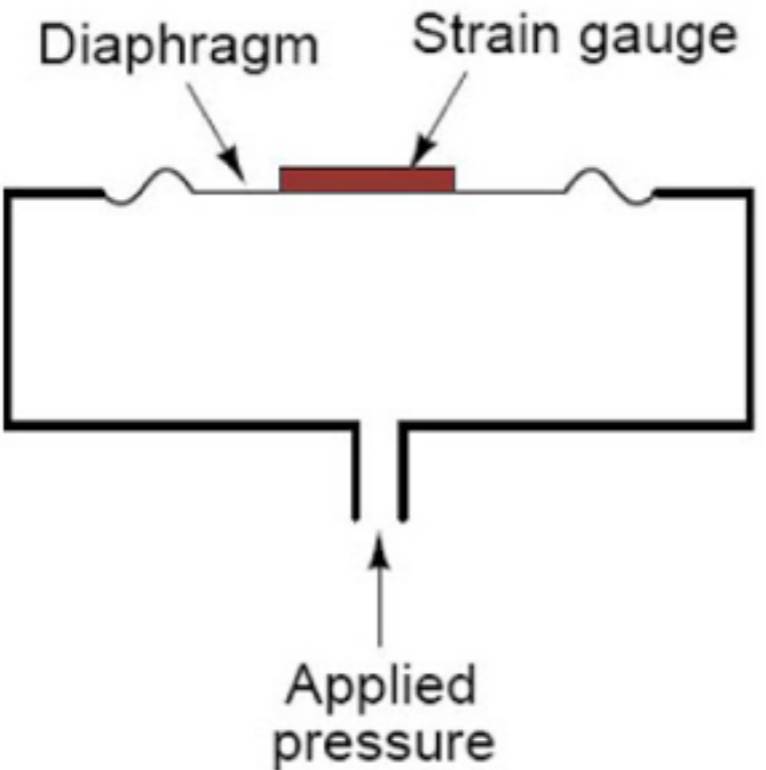
- **Absolute** - measure w.r.t. a perfect vacuum
- **Gage** - measure w.r.t. external (atmospheric) pressure
- **Vacuum** - measure pressures below atmospheric
- **Differential** - measure difference between two points
- **Sealed** - measure w.r.t. a sealed fixed pressure

Housings can vary from PCB mount to industrial



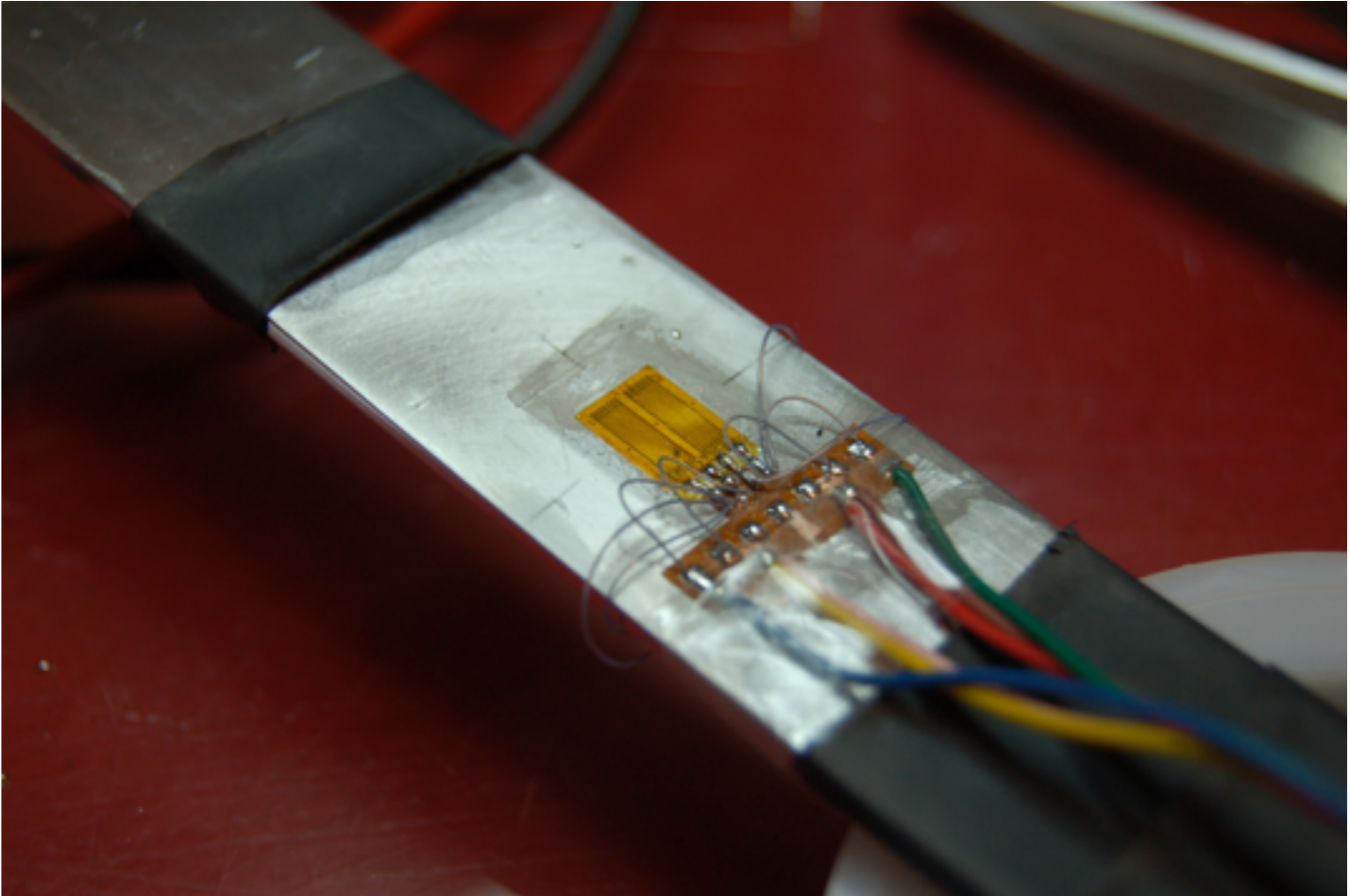
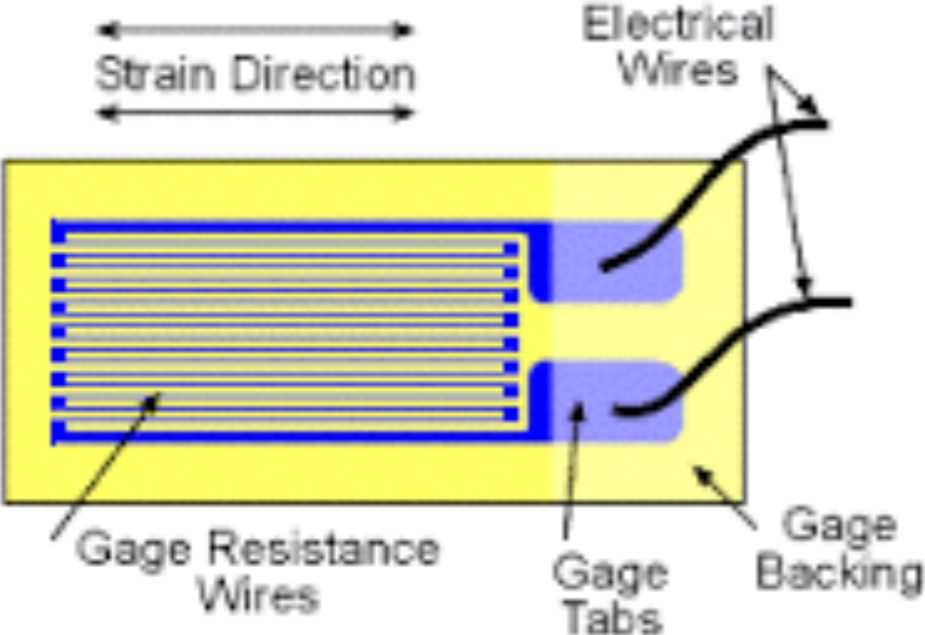
Images: Wikipedia/OMEGA

Pressure sensors are generally a deflection measurement based technology

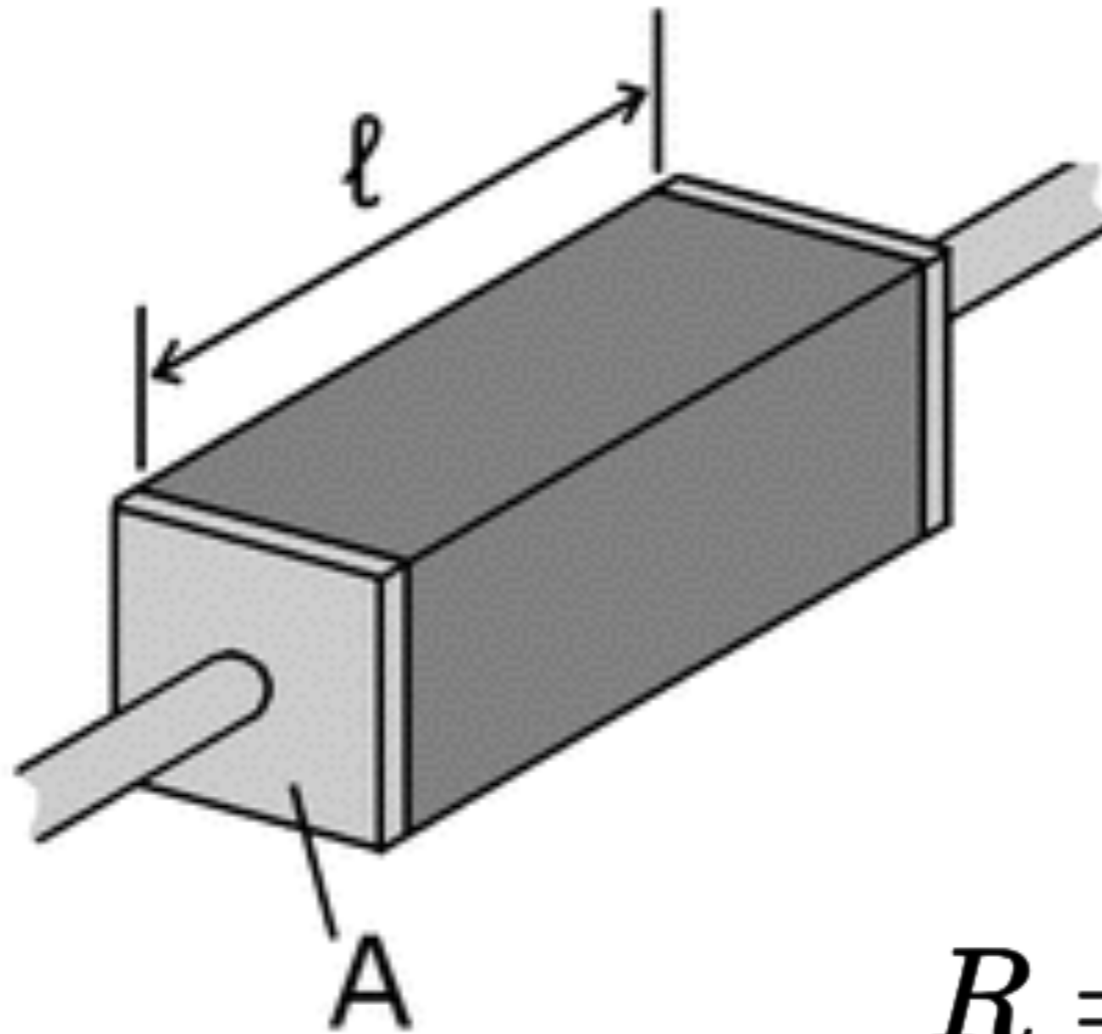


Strain

Strain gages change resistance based upon their stretching/ compression

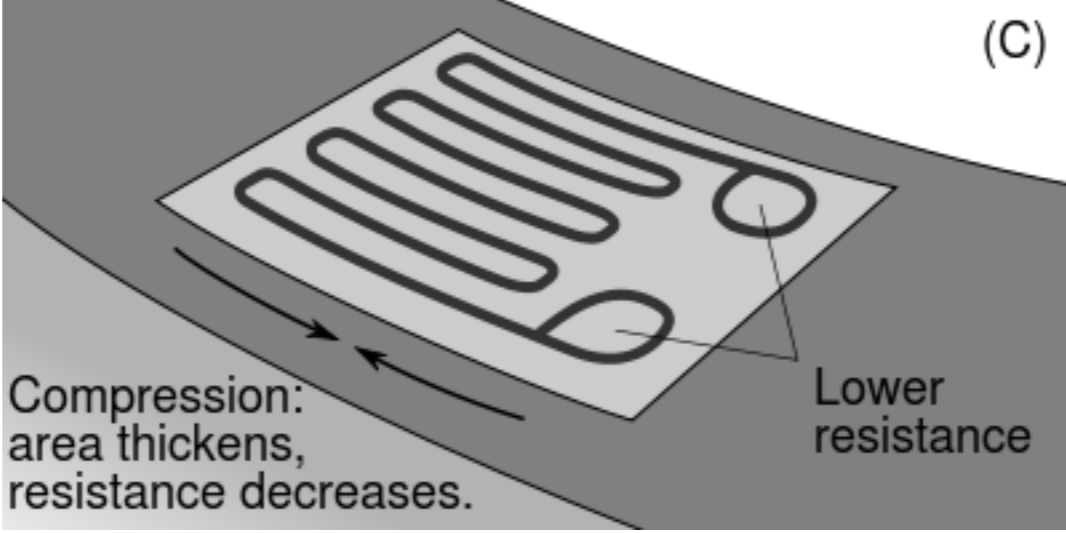
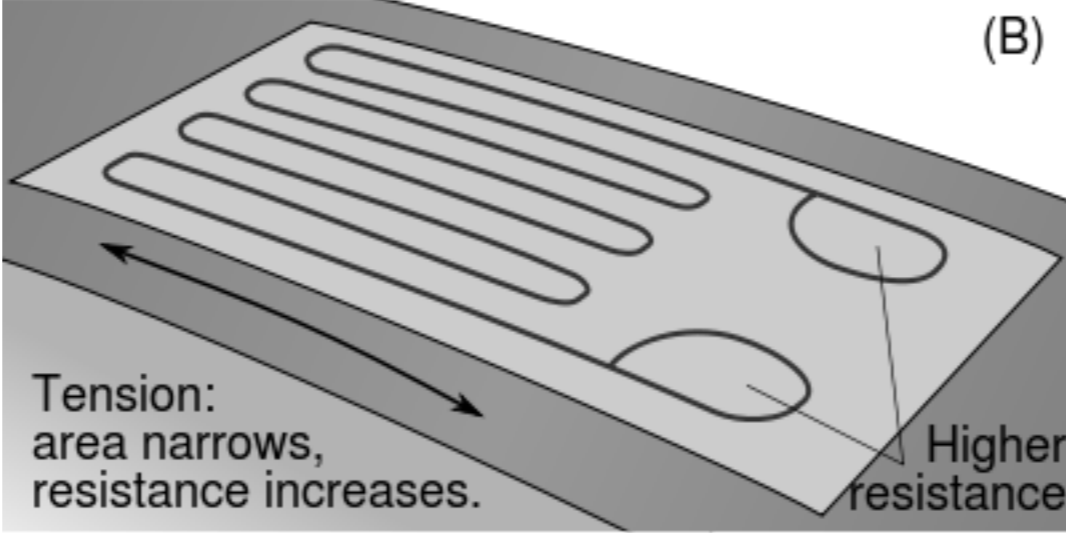
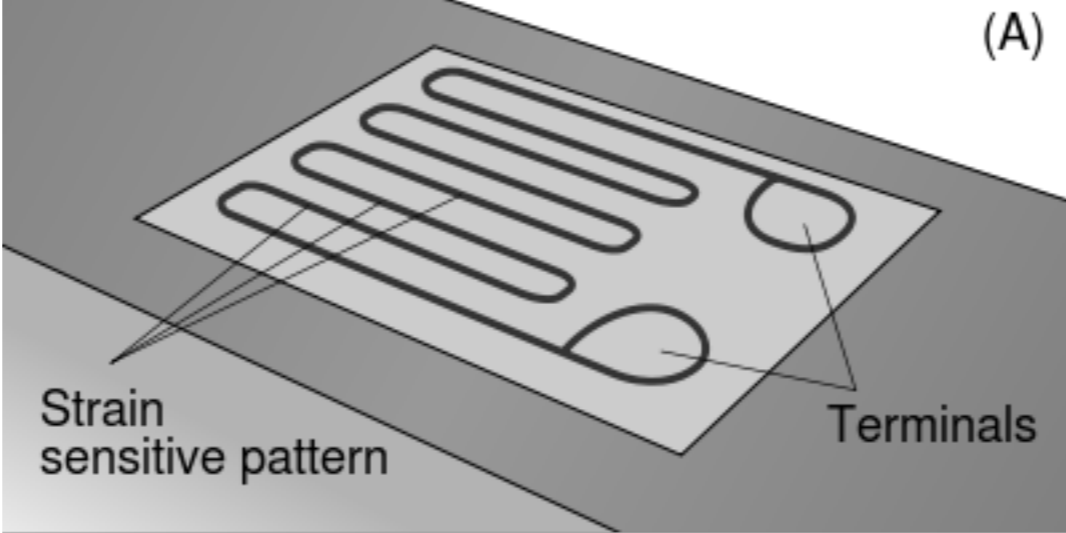


Resistance of a material depends on the area of contact, resistivity, and length

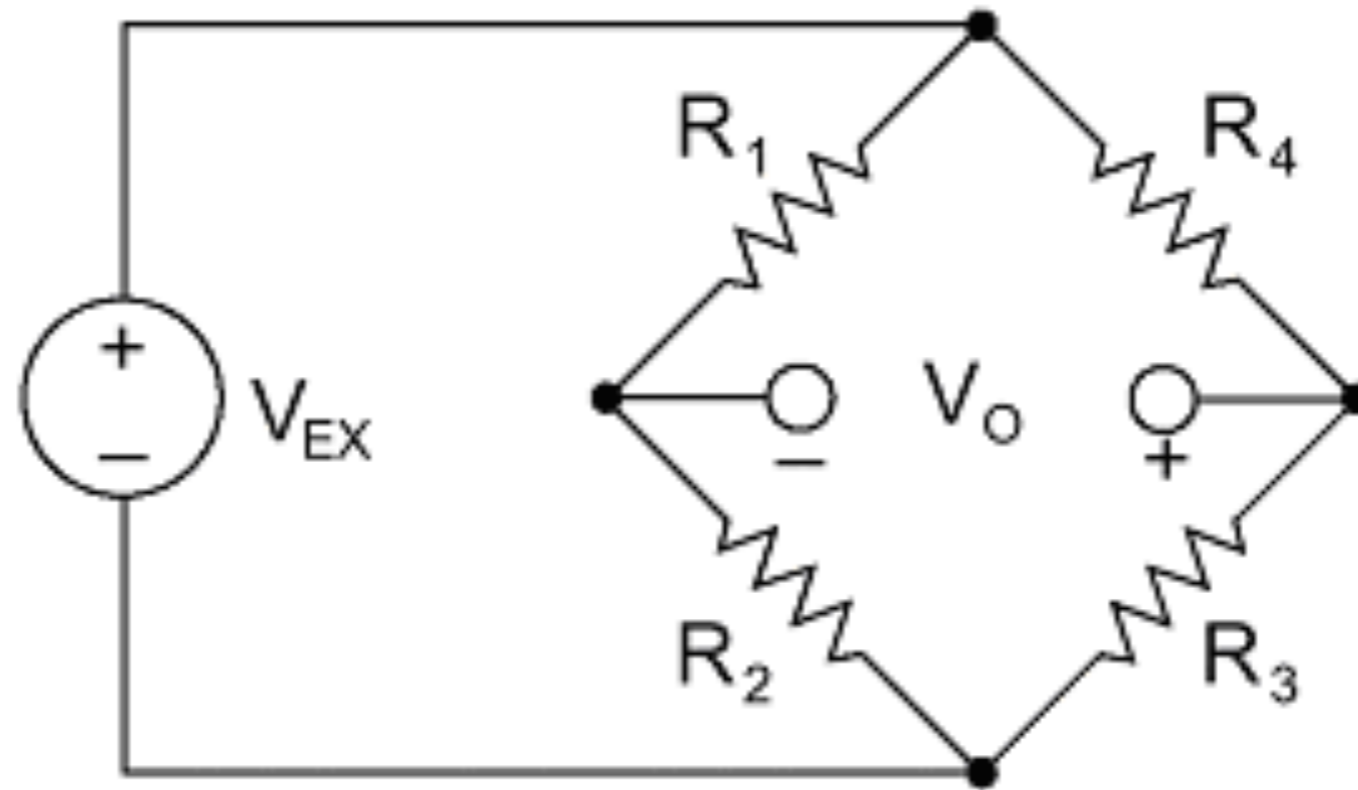


$$R = \rho \frac{l}{A}$$

So tension increases resistance, compression decreases resistance



Most strain gage circuits are based on the Wheatstone Bridge

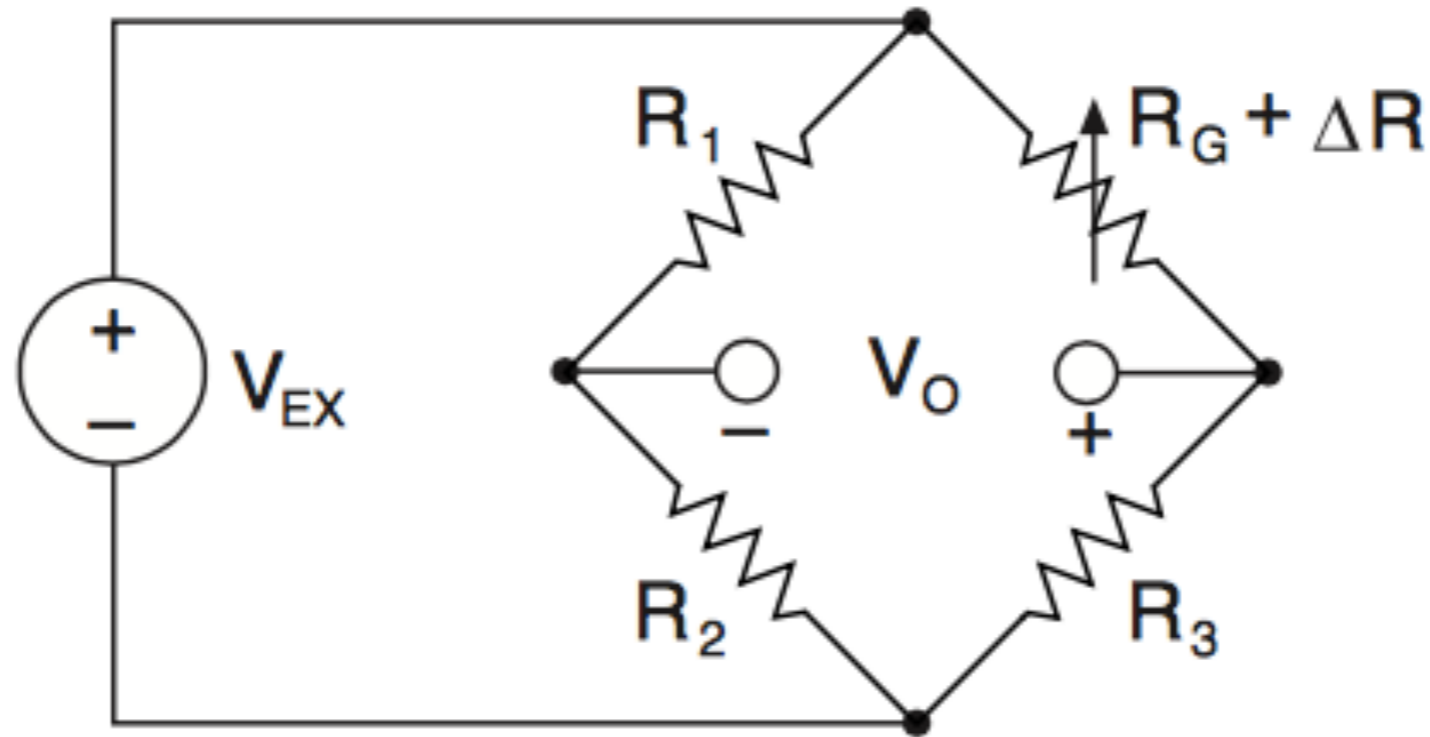


$$V_O = \left[\frac{R_3}{R_3 + R_4} - \frac{R_2}{R_1 + R_2} \right] * V_{EX}$$

The gage factor is the relative change in resistance with strain

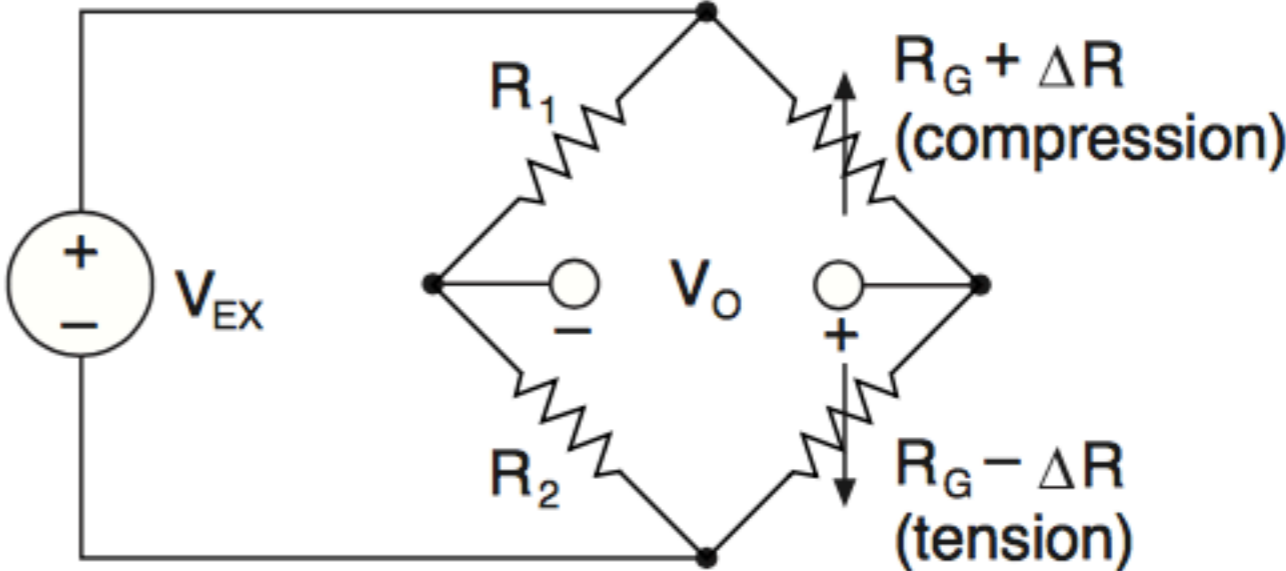
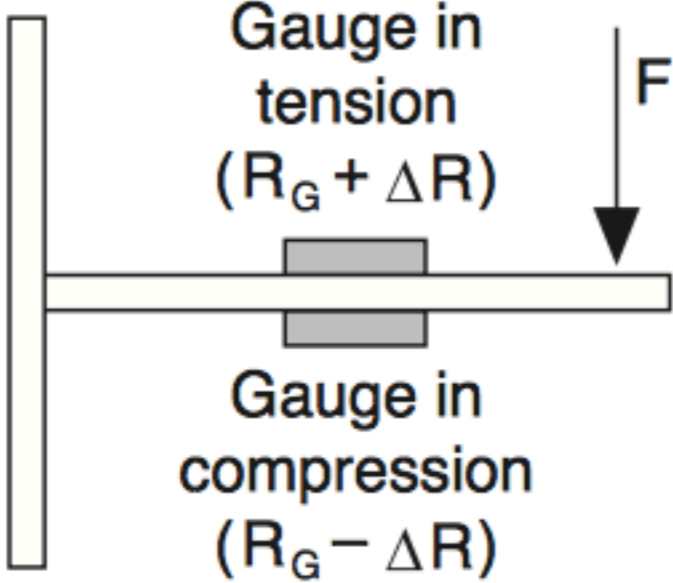
$$GF = \frac{\frac{\Delta R}{R}}{\epsilon}$$

The quarter bridge is the least sensitive, but only requires one active element



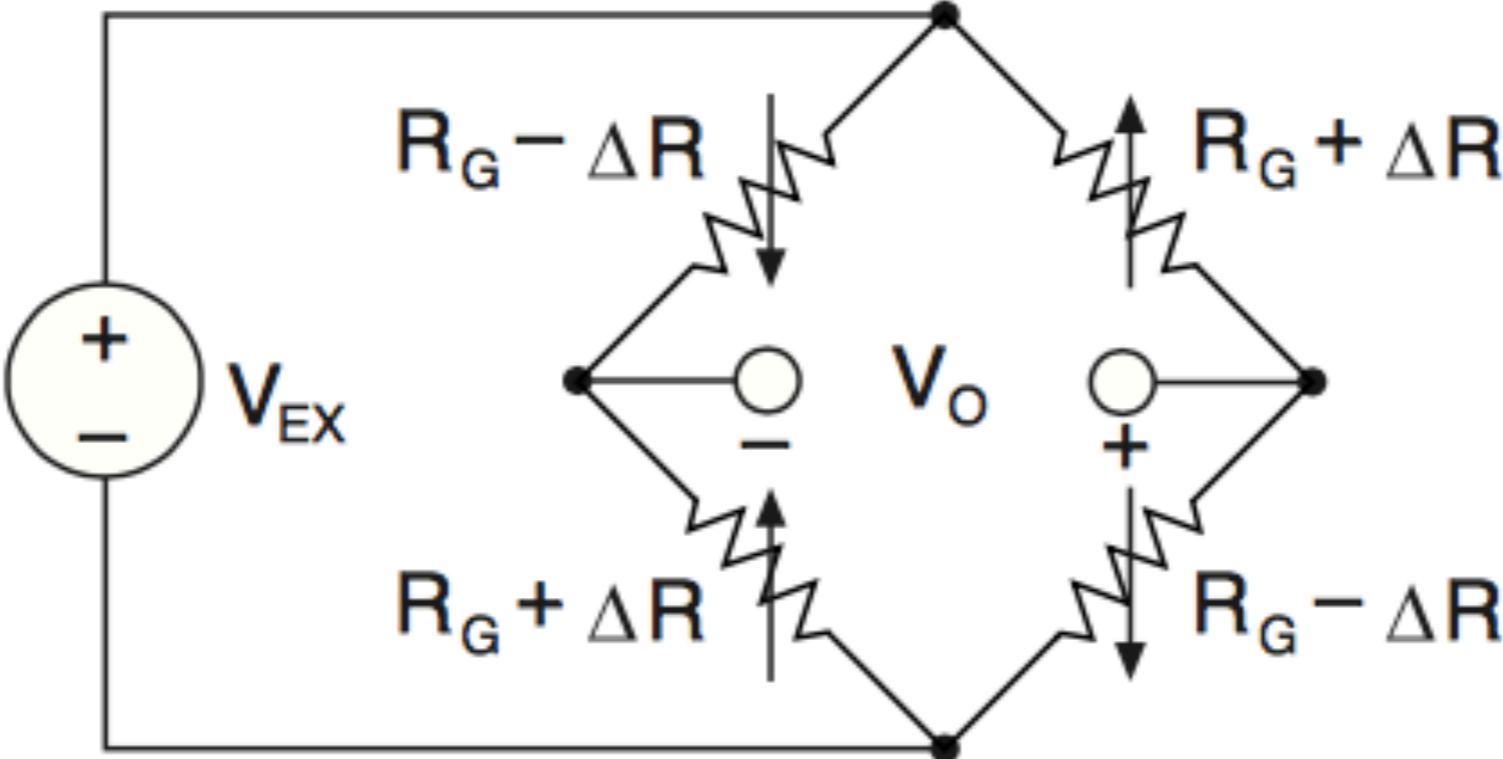
$$\frac{V_O}{V_{EX}} = -\frac{GF \cdot \varepsilon}{4} \left(\frac{1}{1 + GF \cdot \frac{\varepsilon}{2}} \right)$$

Half bridges require only two active elements



$$\frac{V_O}{V_{EX}} = -\frac{GF \cdot \epsilon}{2}$$

The full bridge is the most sensitive arrangement



$$\frac{V_O}{V_{EX}} = -GF \cdot \epsilon$$

Measurement Type	Quarter Bridge		Half-Bridge		Full-Bridge		
	Type I	Type II	Type I	Type II	Type I	Type II	Type III
Axial Strain	Yes	Yes	Yes	No	No	No	Yes
Bending Strain	Yes	Yes	Yes	Yes	Yes	Yes	No
Compensation							
Transverse Sensitivity	No	No	Yes	No	No	Yes	Yes
Temperature	No	Yes	Yes	Yes	Yes	Yes	Yes
Sensitivity							
Sensitivity at 1000 $\mu\epsilon$	~0.5 mV/V	~0.5 mV/V	~0.65 mV/V	~1.0 mV/V	~2.0 mV/V	~1.3 mV/V	~1.3 mV/V
Installation							
Number of Bonded Gages	1	1*	2	2	4	4	4
Mounting Location	Single Side	Single Side	Single Side	Opposite Sides	Opposite Sides	Opposite Sides	Opposite Sides
Number of Wires	2 or 3	3	3	3	4	4	4
Bridge Completion Resistors	3	2	2	2	0	0	0

*A second strain gage is placed in close thermal contact with structure but is not bonded.

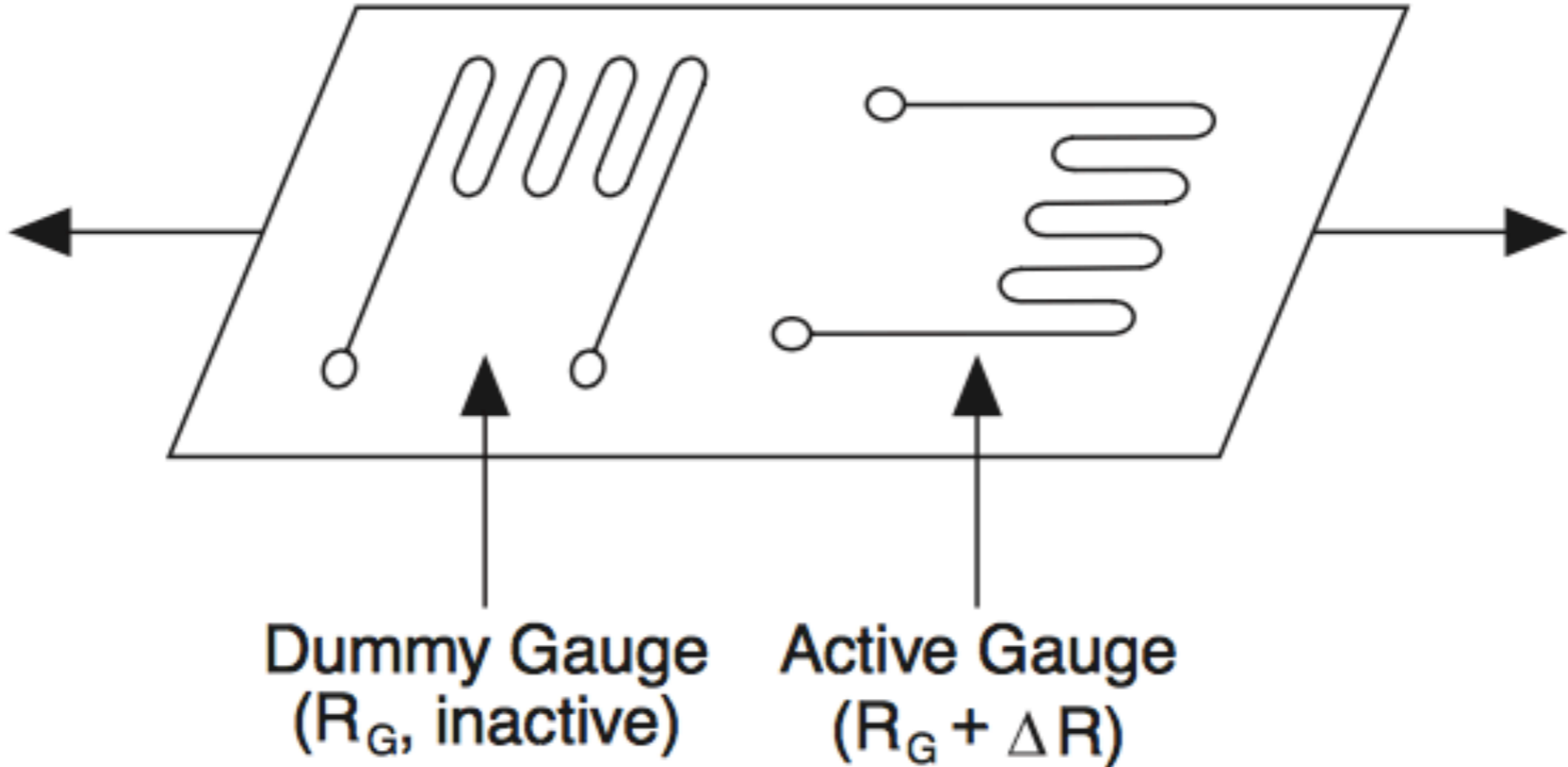
Temperature plays a role as well though

$$\frac{\Delta R}{R} = GF\varepsilon + \alpha\theta$$

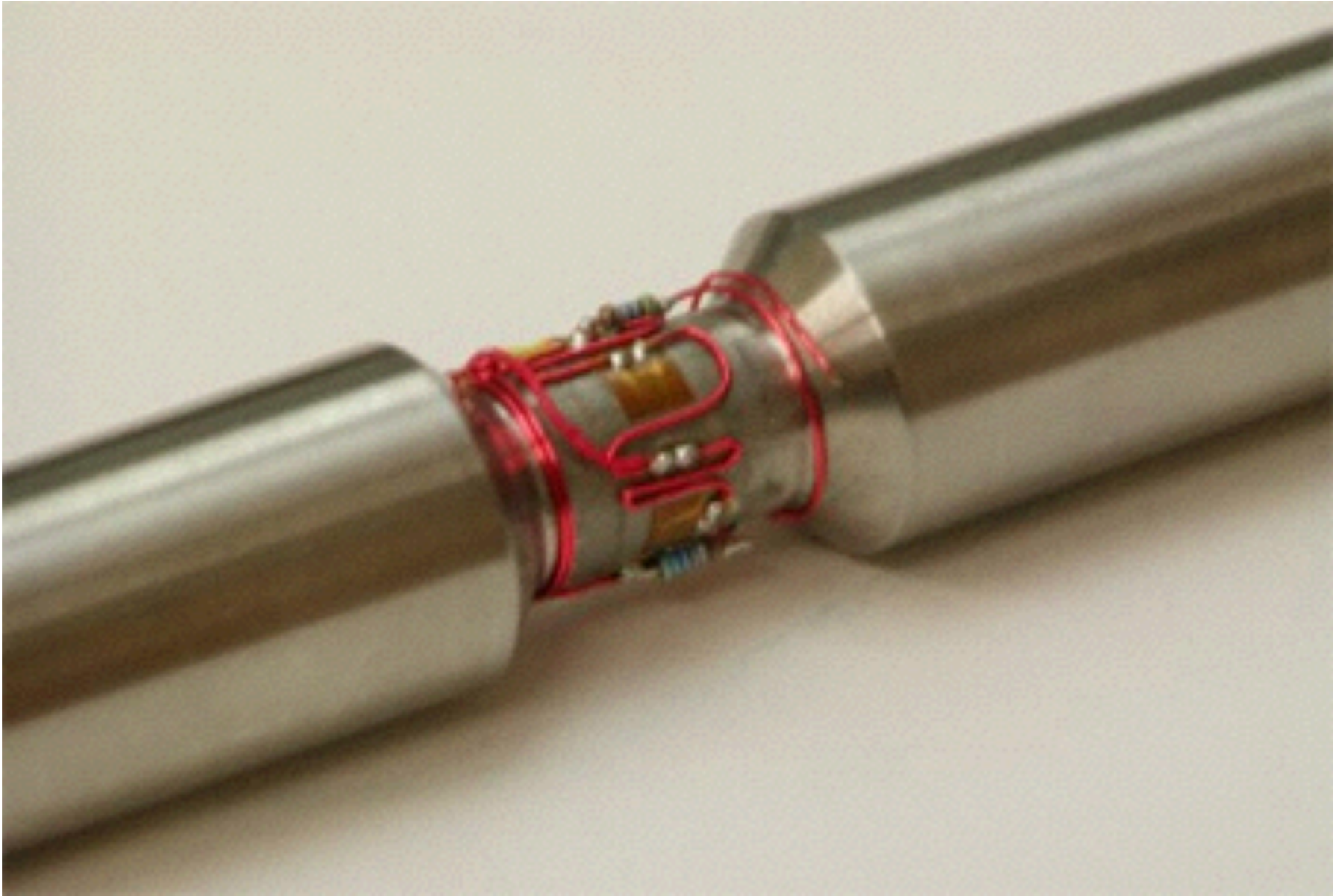
Where

- α = temperature coefficient
- θ = temperature change

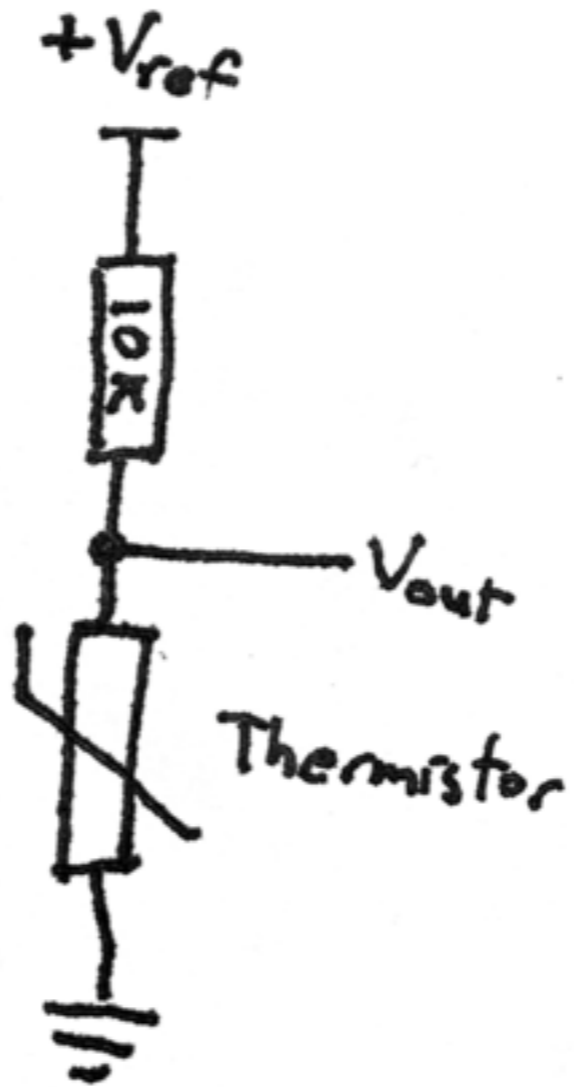
A “dummy gauge” is often used for temperature compensation



Careful wiring and creative placement are often necessary



Activity: Calculate the temperature measurements from the data included with the “Thermistor Calculation” activity



Due : 10/20

Assignment: Find something to affix strain gauges to for our next lab activity



Due : 10/25